Refactoring Scientific Software

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- Individual modules may be cited as *Speaker, Module Title*, in Better Scientific Software tutorial…

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What is Refactoring

Definition: Refactoring is a disciplined technique for restructuring an existing body of code, altering its internal structure without changing its external behavior.

- Different from development
  - You have a working code
  - You know and understand the behavior
  - You have a baseline that you can use for comparison

What is Refactoring

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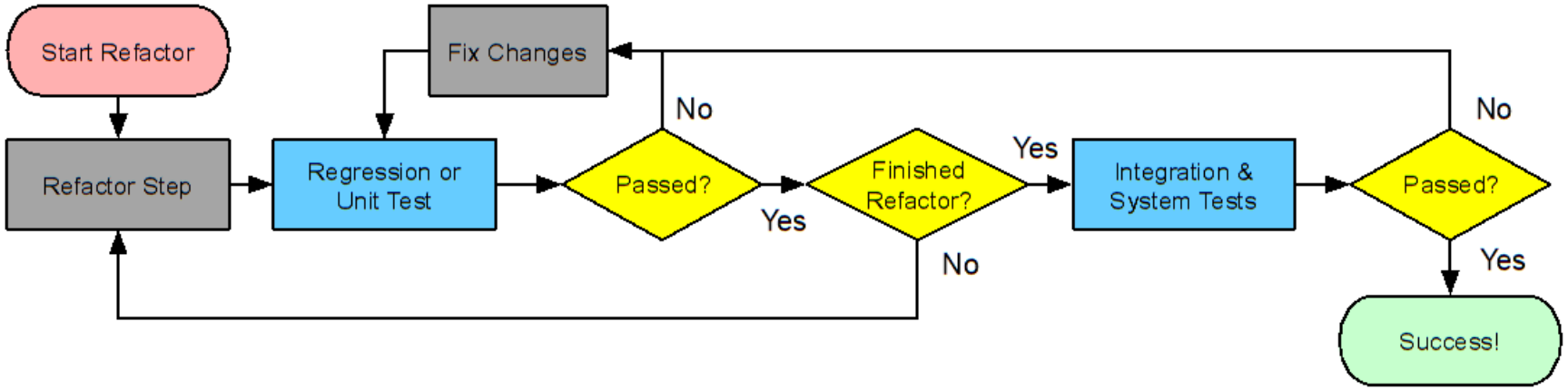
- General motivations
  - Modularity enhancement
    - Improve sustainability
  - Release to outside users
    - Easier to use and understand
  - Port to new platforms
    - Performance portability
  - Expand capabilities
    - Structural flexibility

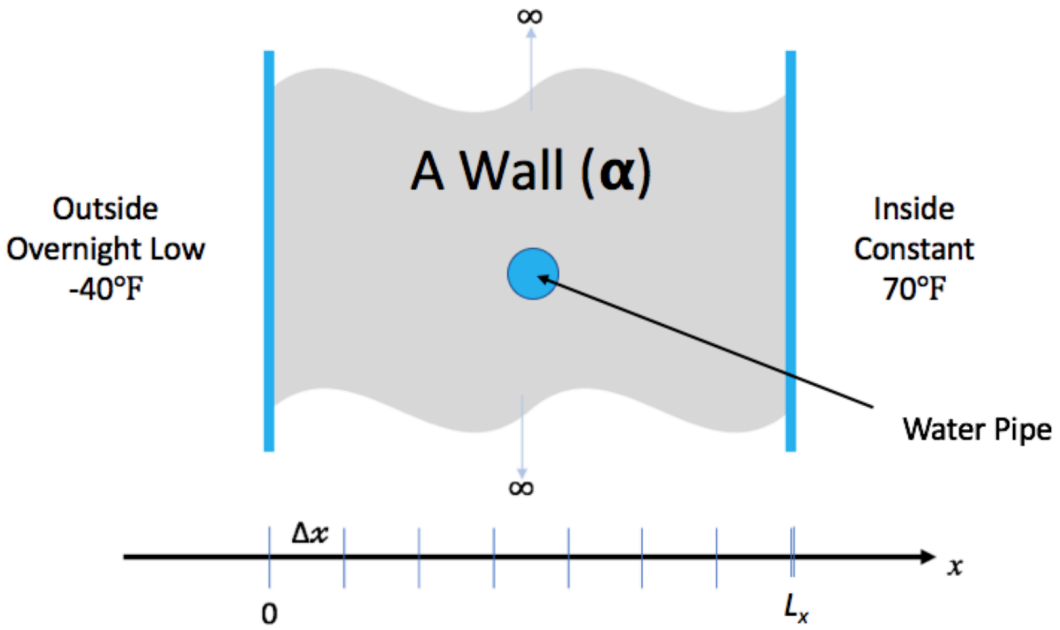
Refactoring

An example of workflow with testing



Look at the Running Example

Lets say you live in a house with exterior walls made of a single material of thickness, $$L_x$$. Inside the walls are some water pipes as pictured below.



You keep the inside temperature of the house always at 70 degrees F. But, there is an overnight storm coming. The outside temperature is expected to drop to -40 degrees F for 15.5 hours. Will your pipes freeze before the storm is over?

In the repository there are two versions

- One is a single file with monolithic code
- The other is modularized reusable maintainable code
- If we had only the first version, we would be refactoring to get to the second

Considerations for Refactoring

- Know why you are refactoring
  - Is it necessary
  - Where should the code be after refactoring
- In heat example version 1
  - It is necessary because
    - It is a monolithic code
    - No reusability of any part of the code
    - Devising tests is hard
    - Limited extensibility
  - Where do we want to be after refactoring
    - Closer to the second version
    - More modular, maintainable and extensible

Considerations for Refactoring

- Know the scope of refactoring
  - How deep a change
  - How much code will be affected
- In heat example
  - No capability extension
  - No performance consideration
  - Cleaner, more maintainable code

To convert the monolithic code

- Separate out utilities, generalize interfaces
- Put global definitions in a header file
- Create a general build function
- No new code or intrusive changes

Before Starting

- Know your cost estimates
- Verification
  - Check for coverage provided by existing tests
  - Develop new tests where there are gaps
  - Make sure tests exist at different granularities
    - There should be demanding integration and system level tests

Before Starting

- Know your cost estimates
- Verification
  - Check for coverage provided by existing tests
  - Develop new tests where there are gaps
  - Make sure tests exist at different granularities
    - There should be demanding integration and system level tests
- Know your bounds
  - on acceptable behavior change
  - error bounds
    - bitwise reproduction of results unlikely after transition
- Map from here to there

Incorporate testing overheads into refactoring cost estimates

Cost estimation

The biggest potential pitfall

- Can be costly itself if the project is large
- Most projects do a terrible job of estimation
  - Insufficient understanding of code complexity
  - Insufficient provisioning for verification and obstacles
  - Refactoring often overruns in both time and budget
- Factors that can help
  - Knowing the scope and sticking to it
    - If there is change in scope estimate again
  - Plan for all stages of the process with contingency factors built-in
  - Make provision for developing tests and other forms of verification
    - Can be nearly as much or more work than the code change
    - Insufficient verification incurs technical debt

Cost estimation

When development and production co-exist

- Potential for branch divergence
- Policies for code modification
  - Estimate the cost of synchronization
  - Plan synchronization schedule and account for overheads
- Anticipate production disruption
  - From code freeze due to merges
  - Account for resources for quick resolution of merge issues

This is where buy-in from the stake-holders is critical

Cost estimation

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- In the heat example
  - No more than a few hours of developer time
  - No disruption
  - No need for a buy-in

This is where buy-in from the stake-holders is critical

Exercise: Refactoring the Running Example

- Convert heatAll.C to the cleaner version with reusable code.
  - Though a solution is there in the repo, your solution need not be identical
  - Think about how you want your final product to be and then go through the exercise of refactoring

- Here as an example exercise, I am taking the clean solution and generalizing the update_solution interface
  - Motivation: Do not want to change heat.C for adding another method
  - For this exercise we will use “ftcs” and “upwind15” as alternative options

Preparing for Refactoring – check coverage

- Run ./heat runame="ftcs_results"
- Run gcov heat.C
- Examine heat.C.gcov

- A dash indicates non-executable line
- A number indicated the times the line was called
- ##### indicates line wasn't exercised

```
HDR = Double.H
SRC = heat.C utils.C args.C exact.C ftcs.C upwind15.C crankn.C
OBJ = $(SRC:.C=.o)
GCOV = $(SRC:.C=.C.gcov) $(SRC:.C=.gcda) $(SRC:.C=.gcno) $(HDR:.
H=.H.gcov)
EXE = heat

# Implicit rule for object files
%.o : %.C
        $(CXX) -c -coverage $(CXXFLAGS) $(CPPFLAGS) $< -o $@

# Linking the final heat app
heat: $(OBJ)
        $(CXX) -coverage -o heat $(OBJ) $(LDFLAGS) -lm
```

```
    -:  143:static bool
  500:  144:update_solution()
    -:  145:{
  500:  146:    if (!strcmp(alg, "ftcs"))
  500:  147:        return update_solution_ftcs(Nx, curr, last, alpha, dx, dt, bc0, bc1);
#####:  148:    else if (!strcmp(alg, "upwind15"))
#####:  149:        return update_solution_upwind15(Nx, curr, last, alpha, dx, dt, bc0, bc1);
#####:  150:    else if (!strcmp(alg, "crankn"))
#####:  151:        return update_solution_crankn(Nx, curr, last, cn_Amat, bc0, bc1);
#####:  152:    return false;
  500:  153:}
    -:  154:
    -:  155:static Double
  500:  156:update_output_files(int ti)
    -:  157:{
  500:  158:    Double change;
    -:  159:
  500:  160:    if (ti>0 && save)
    -:  161:    {
#####:  162:        compute_exact_solution(Nx, exact, dx, ic, alpha, ti*dt, bc0, bc1);
#####:  163:        if (savi && ti%savi==0)
#####:  164:            write_array(ti, Nx, dx, exact);
#####:  165:    }
```

Preparing for Refactoring – get baselines

- Call to upwind15 not exercised
- Run ./heat alg="upwind15" runame="upwind_results

```
    -:  143:static bool
  500:  144:update_solution()
    -:  145:{
  500:  146:    if (!strcmp(alg, "ftcs"))
#####:  147:        return update_solution_ftcs(Nx, curr, last, alpha, dx, dt, bc0, bc1);
  500:  148:    else if (!strcmp(alg, "upwind15"))
  500:  149:        return update_solution_upwind15(Nx, curr, last, alpha, dx, dt, bc0, bc1);
#####:  150:    else if (!strcmp(alg, "crankn"))
#####:  151:        return update_solution_crankn(Nx, curr, last, cn_Amat, bc0, bc1);
#####:  152:    return false;
  500:  153:}
    -:  154:
```

- We have baselines for ftcs and upwind

```
[ahilya:clean dubey$ ls ftcs_results/
clargs.out                      ftcs_results_soln_00000.curve   ftcs_results_soln_final.curve
[ahilya:clean dubey$ ls upwind_results/
clargs.out                      upwind_results_soln_00000.curve upwind_results_soln_final.curve
ahilya:clean dubey$
```

Refactoring – The starting code

```
extern bool
update_solution_ftcs(int n,
    Double *curr, Double const *last,
    Double alpha, Double dx, Double dt,
    Double bc_0, Double bc_1);

extern bool
update_solution_upwind15(int n,
    Double *curr, Double const *last,
    Double alpha, Double dx, Double dt,
    Double bc_0, Double bc_1);

extern bool
update_solution_crankn(int n,
    Double *curr, Double const *last,
    Double const *cn_Amat,
    Double bc_0, Double bc_1);
```

```
if (!strncmp(alg, "crankn", 6))
    initialize_crankn(Nx, alpha, dx, dt, &cn_Amat);
```

- Interfaces are not identical
- crankn has an extra argument
- It also has an extra step in initialization

Refactoring

- Generalize the interface

```
extern bool
update_solution(int n,
    Double *curr, Double const *last,
    Double alpha, Double dx, Double dt,
    Double const *cn_Amat,
    Double bc_0, Double bc_1);
```

- Modify the makefile

Refactoring

- Generalize the interface

```
extern bool
update_solution(int n,
    Double *curr, Double const *last,
    Double alpha, Double dx, Double dt,
    Double const *cn_Amat,
    Double bc_0, Double bc_1);
```

- Modify the makefile

```
HDR = Double.H
SRC1 = heat.C utils.C args.C exact.C ftcs.C
SRC2 = heat.C utils.C args.C exact.C upwind15.C
SRC3 = heat.C utils.C args.C exact.C crankn.C
OBJ1 = $(SRC1:.C=.o)
OBJ2 = $(SRC2:.C=.o)
OBJ3 = $(SRC3:.C=.o)

EXE1 = heat1
EXE2 = heat2
EXE3 = heat3
```

Refactoring

- Generalize the interface

```
extern bool
update_solution(int n,
    Double *curr, Double const *last,
    Double alpha, Double dx, Double dt,
    Double const *cn_Amat,
    Double bc_0, Double bc_1);
```

- Modify the makefile
- Add null implementations of initialize_crank in ftcs and upwind15

```
HDR = Double.H
SRC1 = heat.C utils.C args.C exact.C ftcs.C
SRC2 = heat.C utils.C args.C exact.C upwind15.C
SRC3 = heat.C utils.C args.C exact.C crankn.C
OBJ1 = $(SRC1:.C=.o)
OBJ2 = $(SRC2:.C=.o)
OBJ3 = $(SRC3:.C=.o)

EXE1 = heat1
EXE2 = heat2
EXE3 = heat3
```

Refactoring

```
void
initialize_crankn(int n,
    Double alpha, Double dx, Double dt,
    Double **_cn_Amat)
{
}

bool
update_solution(int n, Double *curr, Double const *last,
    Double alpha, Double dx, Double dt,
    Double const *cn_Amat,
    Double bc_0, Double bc_1)
{
    Double const f2 = 1.0/24;
    Double const f1 = 1.0/6;
    Double const f0 = 1.0/4;
    Double const k = alpha * alpha * dt / (dx * dx);
    Double const k2 = k*k;
```

- make heat1
- Run ./heat runame="ftcs_results"
- Make heat2
- Run ./heat runame="upwind_results"
- Verify against baseline

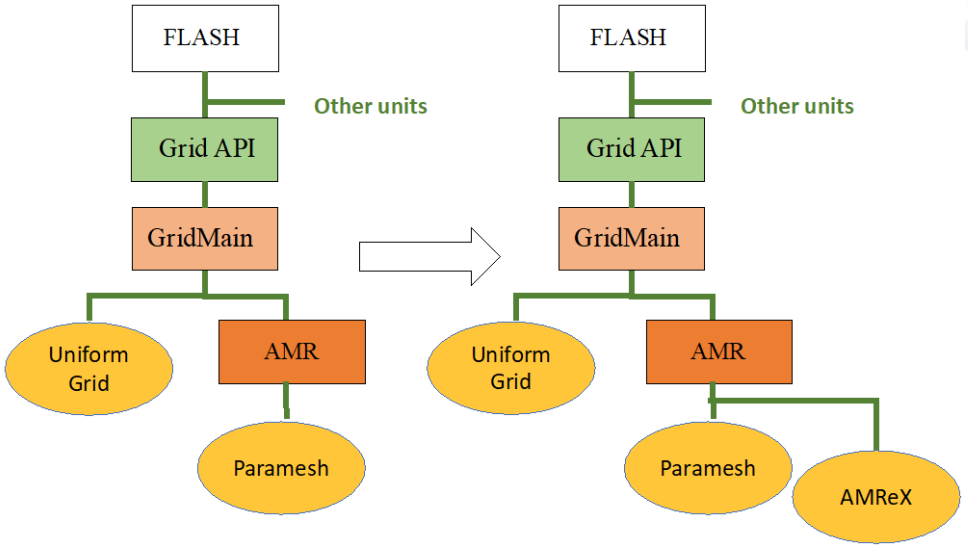
A Real World Example: FLASH

Refactoring for Next Generation Hardware

AMReX - Lawrence Berkeley National Lab
- Designed for exascale
- Node-level heterogeneity
- Smart iterators hide parallelization

Goal: Replace Paramesh with AMReX

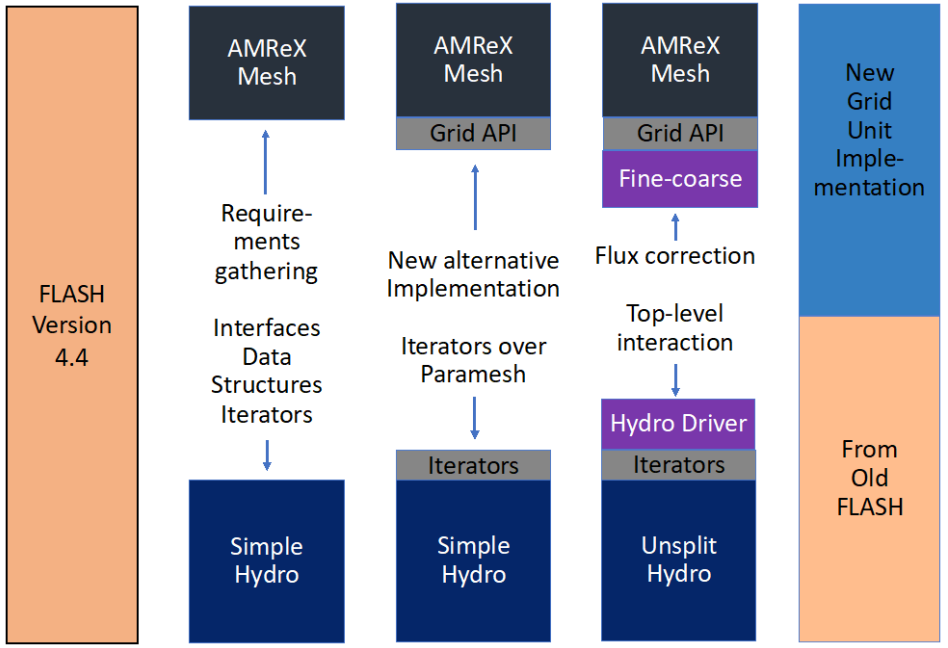
Plan: Getting there from here
- On ramping
- Design
- Intermediate steps
- Realizing the goal



Considerations

- Cost estimation
  - Expected developer time
  - Extent of disruption in production schedules
- Get a buy-in from the stakeholders
  - That includes the users
  - For both development time and disruption

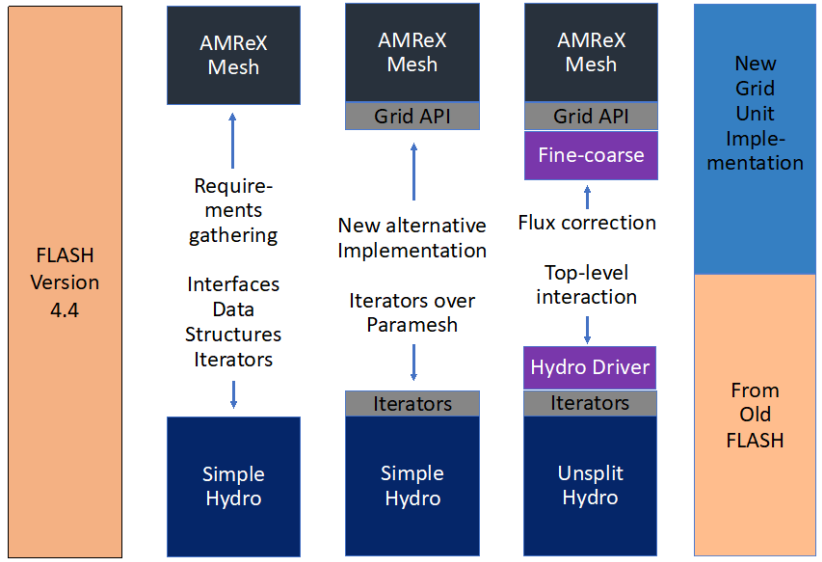
- In FLASH
  - Initial estimate at 6-12 months
  - Took close to 12 months



Phase 1 - design

Sit, think, hypothesize, & argue

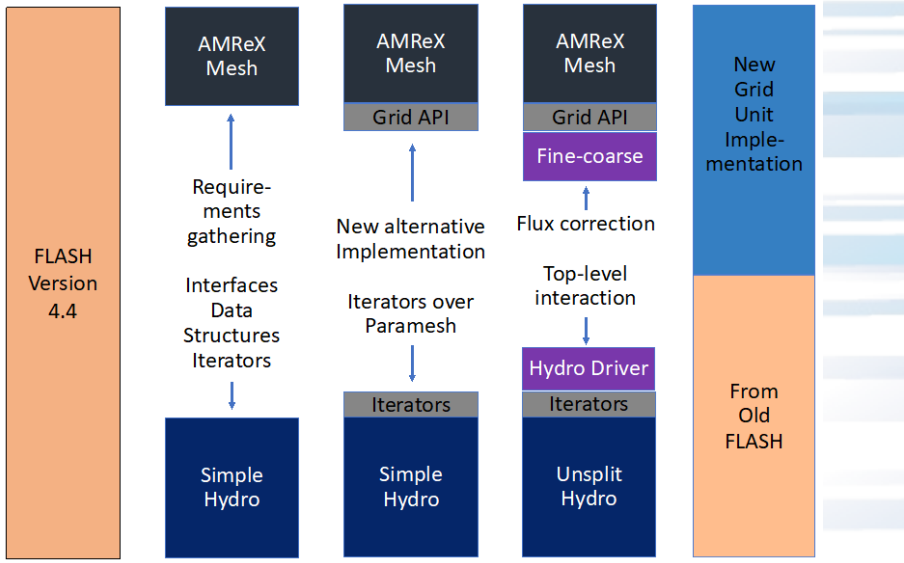
- Derive and understand principal definitions & abstractions
- Collect & understand Paramesh/AMReX constraints
  - Generally useful design due to two sets of constraints?
- Collect & understand physics unit requirements on Grid unit
- Design fundamental data structures & update interface



Phase 2 - prototyping

Quick, dirty, & light

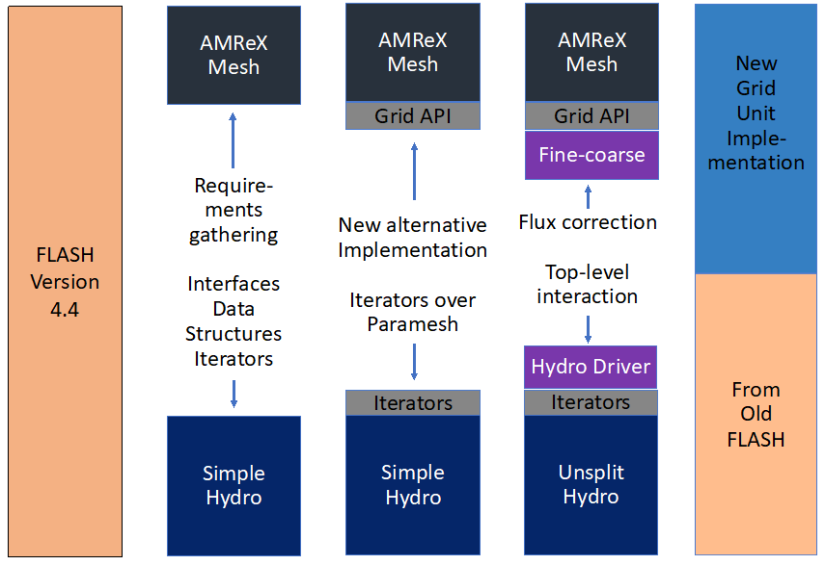
- Implement new data structures
  - Evolve design/implementation by iterating between Paramesh & AMReX
- Explore Grid/physics unit interface
  - `simpleUnsplit` Hydro unit
  - A simplified implementation
    - No need to be physically correct
    - Exercise the grid interface identically to the real solver
- Discover use patterns of data structures and Grid unit interface
- Adjust requirements & interfaces



Phase 3 - implementation

Toward quantifiable success & Continuous Integration

- Derive & implement lessons learned
  - Clean code & inline documentation
- Update `Unsplit` Hydro
- Intermediate step - Hybrid FLASH
  - AMReX manages data
  - Paramesh drives AMR
- Fully-functioning simulation with AMReX
- Prune old code



TO HAVE GOOD OUTCOME FROM REFACTORING

1. KNOW WHY
2. KNOW HOW MUCH
3. KNOW THE COST
4. PLAN
5. HAVE STRONG TESTING AND VERIFICATION
6. GET BUY-IN FROM STAKEHOLDERS