SHF: Small: Collaborative Research: Transform-to-perform: languages, algorithms, and solvers for nonlocal operators

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Nonlocal Operators

Very broad class of mathematical operations, targeted examples:

- Layer potentials
- Volume potentials
- Fractional derivatives

$$u(\mathbf{x}) = \int_{\Omega} K(\mathbf{x}, \mathbf{y}) \sigma(\mathbf{y}) \mathrm{d}\mathbf{y},$$

Inputs:

- \square Ω a (volume or surface) source geometry, given as a high-order mapped, unstructured mesh for geometric flexibility
- kernel $K(\mathbf{x}, \mathbf{y})$, as a math. expression,
- density $\sigma(\mathbf{y})$ as input data,
- **x** as target var., **y** as source var.

Non-Local Operators are increasingly used in coupled simulations with conventional derivative/PDE-based modeling. Derivatives are local operators.

NUFL

An extension of UFL to nonlocal operators: k = Parameter("k")

```
x = TargetVariable(ambient_dim=2)
```

```
y = SourceVariable(ambient_dim=2)
kernel = ExpressionKernel(
  1/(2*pi)*hankel_1_0(
    k * sqrt((x-y)@(x-y))))
```

```
wspace = FunctionSpace(
  Surface(mesh), "Lagrange", 3)
w = Function (wspace)
v = TestFunction(wspace)
bdry_op_sym = inner(
  -0.5 * w
  + kernel.conv(w)
 - (grad(y)(kernel)
```

Results: Surface Potentials

An exterior, moderate-frequency Helmholtz problem in complex geometry:



Linearly scaling fast algorithm

Predictable error behavior

Results: Volume Potentials



Background: Firedrake/UFL

- Finite Elements: PDEs/derivatives modeled via a variational form
 - on computational meshes representing geometry
- UFL: A DSL for expressing variational forms
- Firedreake: A framework for high-performance UFL evaluation at scale



V1 = FunctionSpace(mesh, 'RT', 1)V2 = FunctionSpace(mesh, 'DG', 0)W = V1 * V2u, p = TrialFunctions(W)v, q = TestFunctions(W)f = Function(V2)a = (p*q - q*div(u))+ inner(v, u)

- @ FacetNormal(mesh)).conv(w), v) * dx
- Allows seamless integration of local/nonlocal modeling
- Layer potentials, fractional derivatives, and conventional FEM all "under one roof"

Computational realization:

- Pytential with GIGAQBX TS fast algorithm [Wala, Klöckner '20] for surface potentials
- Volumential for volume potentials

Fractional Derivatives

Example: Fractional Laplacian

$$(-\triangle)^{s}u(x) = \frac{2^{2s} \Gamma(s+n/2)}{\pi^{n/2} \Gamma(1-s)}$$
$$\mathsf{PV} \int_{\Omega} \frac{u(x) - u(y)}{\|x-y\|_{2}^{n+2s}} \mathrm{d}y$$

Shortcoming in many computational experiments so far: no fast algorithm, $O(N^2)$ scaling.

Idea: "a volume potential with odd kernel" **Reality:** More complex, but not too far

Solvers, Symbolic/HSS Matrix Integration

An interior Poisson problem in complex geometry:



- Linearly scaling fast algorithm
- Predictable error behavior

Results: Domain Truncation



+ div(v)*p*dx L = f * q * dxu = Function(W)solve(a = L, u)

https://firedrakeproject.org

Background: Fast Algorithms

Naive evaluation of non-local operators requires $O(N^2)$ operations:

Not scalable

Not computationally feasible in 3D

Needs *fast algorithms* such as variants of Fast Multipole, making use of compressibility of far-field interactions.



Successful solution of a coupled FEM/non-local system of equations requires sophisticated solver technology.

Example: Nonloccal operators can precondition themselves and FEM systems. Important to represent nonlocal operators in matrix form. For example as Hierarchically Semiseparable Matrices. **Idea:** Extend UFL to represent solver infrastructure:

- matrix-free/HSS/sparse
- Schur complements
- Preconditioners



(shaded blocks have low rank)

- $(\nabla u, \nabla v) \kappa^2 (u, v) i\kappa \langle u, v \rangle_{\Sigma}$ $+\langle (i\kappa - \frac{\partial}{\partial n}) D(u), v \rangle_{\Sigma}$ $= \langle f, \mathbf{v} \rangle_{\Gamma} + \langle (i\kappa - \frac{\partial}{\partial \mathbf{v}}) S(f), \mathbf{v} \rangle_{\Sigma}$
- PML complicates solvers
- Retain ellipticity, optimal error estimates + preconditioners
- Impl.: Firedrake + Pytential
 - (NUFL: future work)

Summary

- Local+nonlocal modeling: attractive but technically complex
 - Moreso in complex geometry
- Computational tools will help make this field more accessible
- Fast algorithms for matvecs and solvers will ensure computational scalability

