

Optimal Control of Forest Disease Using Individual-Based Models

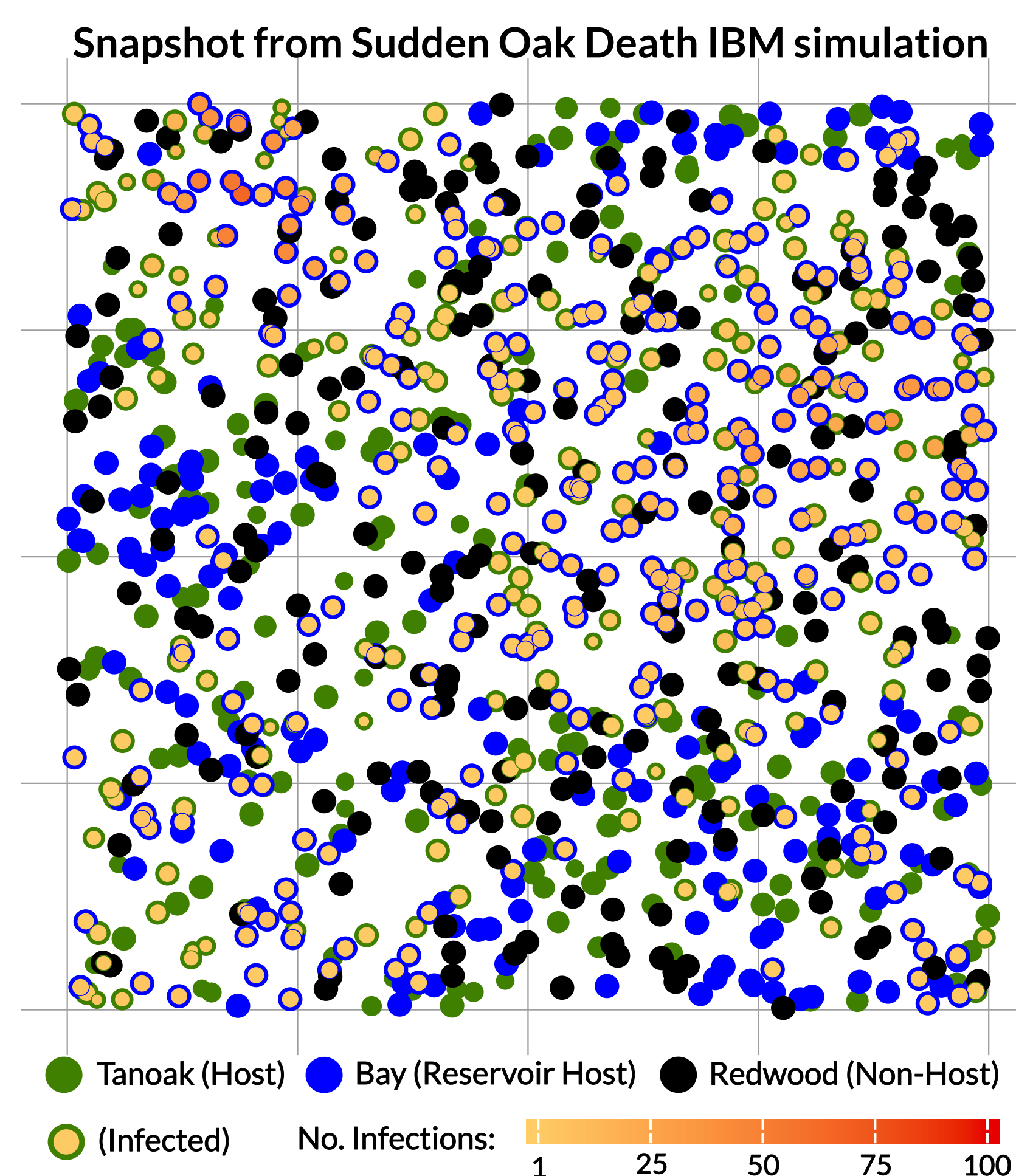
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Background:

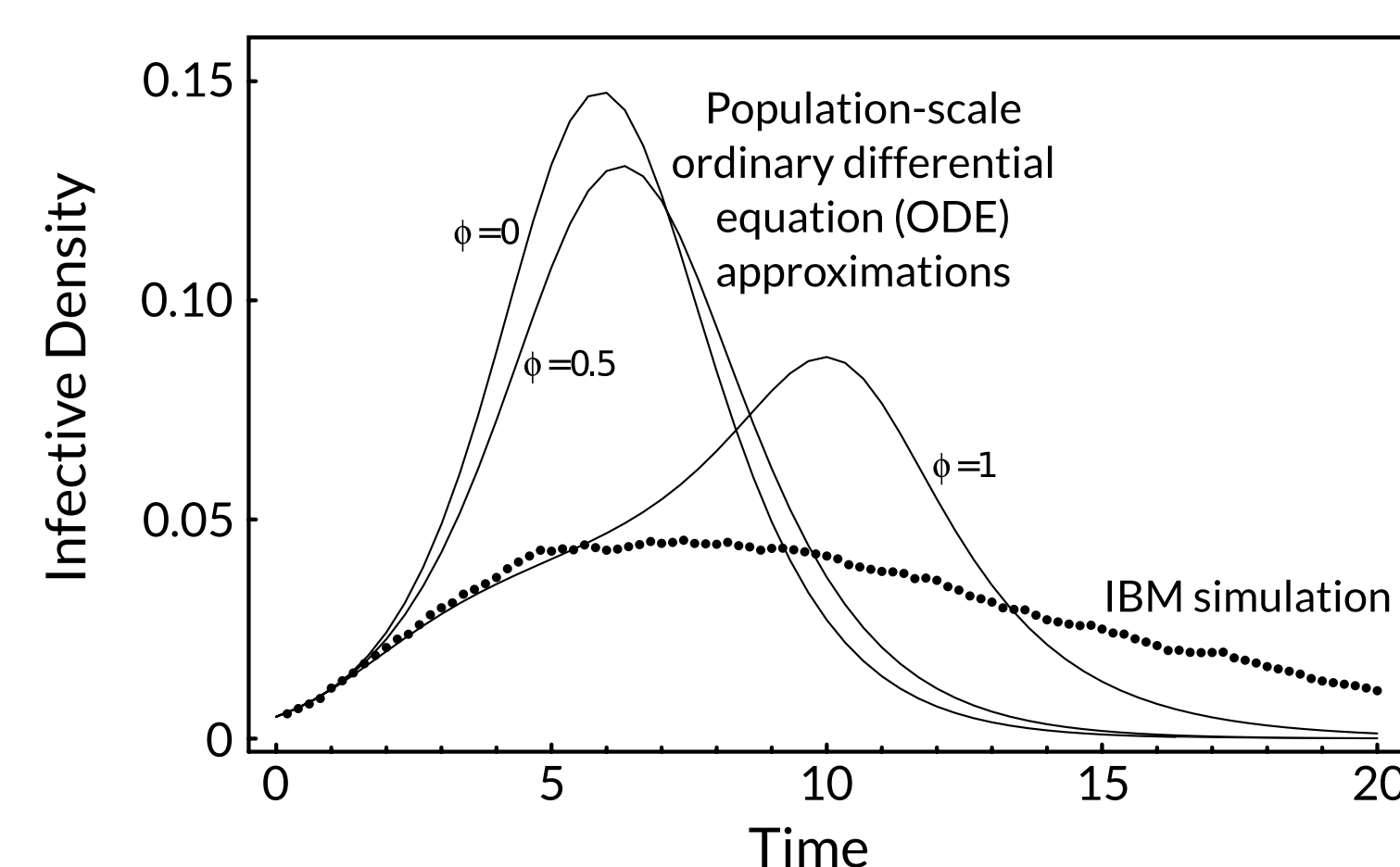
Sudden Oak Death (SOD) is an invasive disease fatal to many oaks, especially tanoak (*Notholithocarpus densiflorus*), a species with important ecological and cultural values in coastal forests of California and Oregon.

Epidemiology of SOD is complex. The effect of the pathogen (*Phytophthora ramorum*) varies widely by tree species and size (Cobb et al. 2012). Rain-splash dispersal and spatial heterogeneity of hosts leads to considerable spatial structure within stands. Thus, an **individual-based model (IBM)** is useful in simulating disease dynamics.



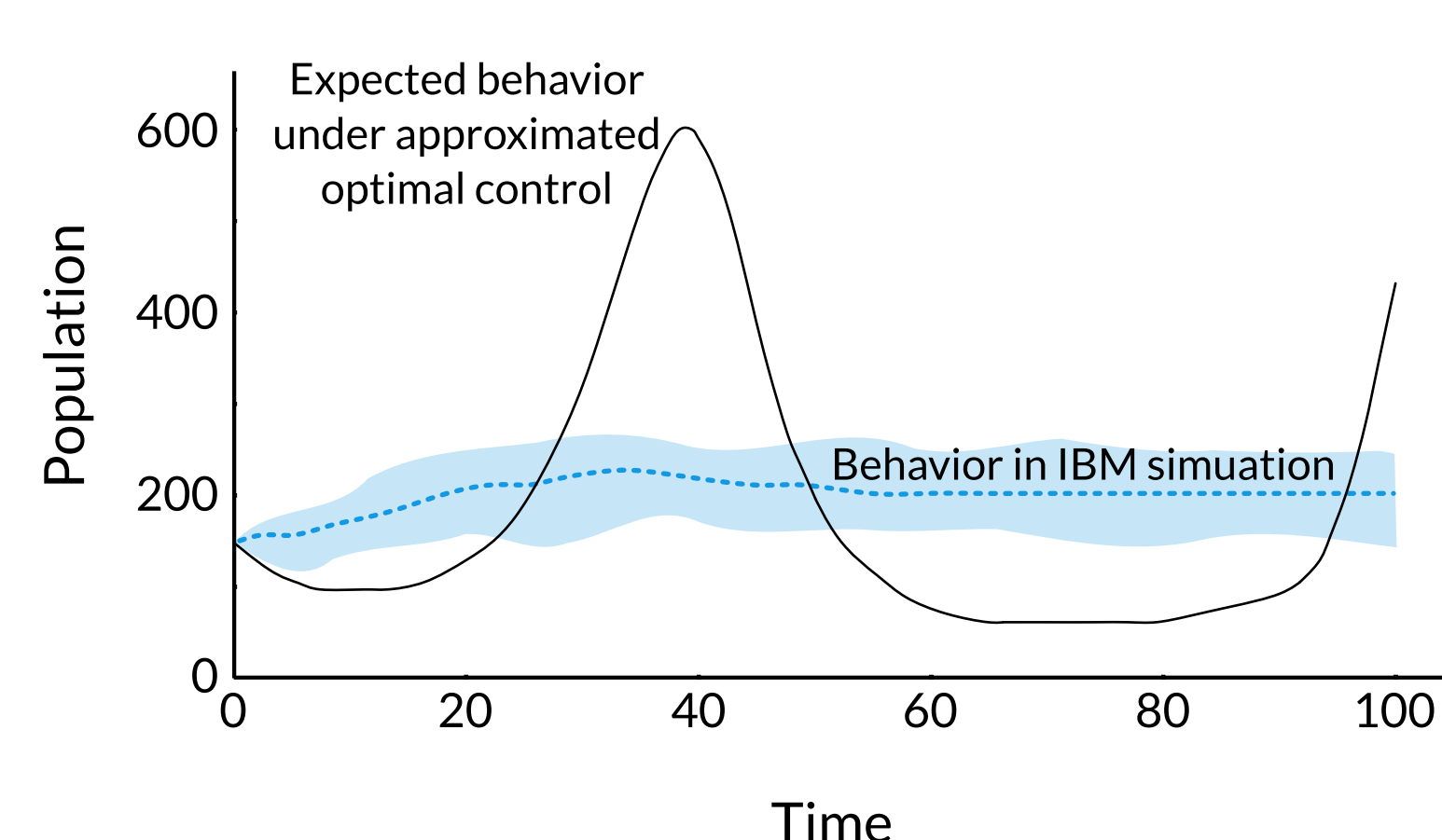
However, analysis of IBMs is challenging, as many are not well represented at the population scale with closed-form equations.

Closed-form approximations poorly capture disease dynamics in a spatial IBM (Brown and Bolker 2004)



In particular, IBMs challenge optimal control methods, as their state space is large and highly multidimensional. Control based on approximation can lead to incorrect outcomes.

Outcome of optimal control on an ODE-based IBM approximation (Federico et al. 2013)



Method: A Multi-Scale Approach to Dynamic Optimization

To solve optimal control problems in an IBM context, I am developing a method that combines the **multi-scale** or **equation-free** framework (Kevrekidis and Samaey 2009), with traditional dynamic optimization techniques from natural resource economics. This allows optimization of the mean behavior of an IBM, even if it can only be accessed as a "black box".

Define the **Hamiltonian optimization problem** at a coarse (population) scale

$$\underbrace{\max_h}_{\text{Find the control path that maximizes...}} \underbrace{\mathcal{H}}_{\text{value of using resource}} = \underbrace{\pi(S, h, t)}_{\text{Profit function}} + \underbrace{\lambda f(S, h, t)}_{\text{change in value of resource to future profits}}$$

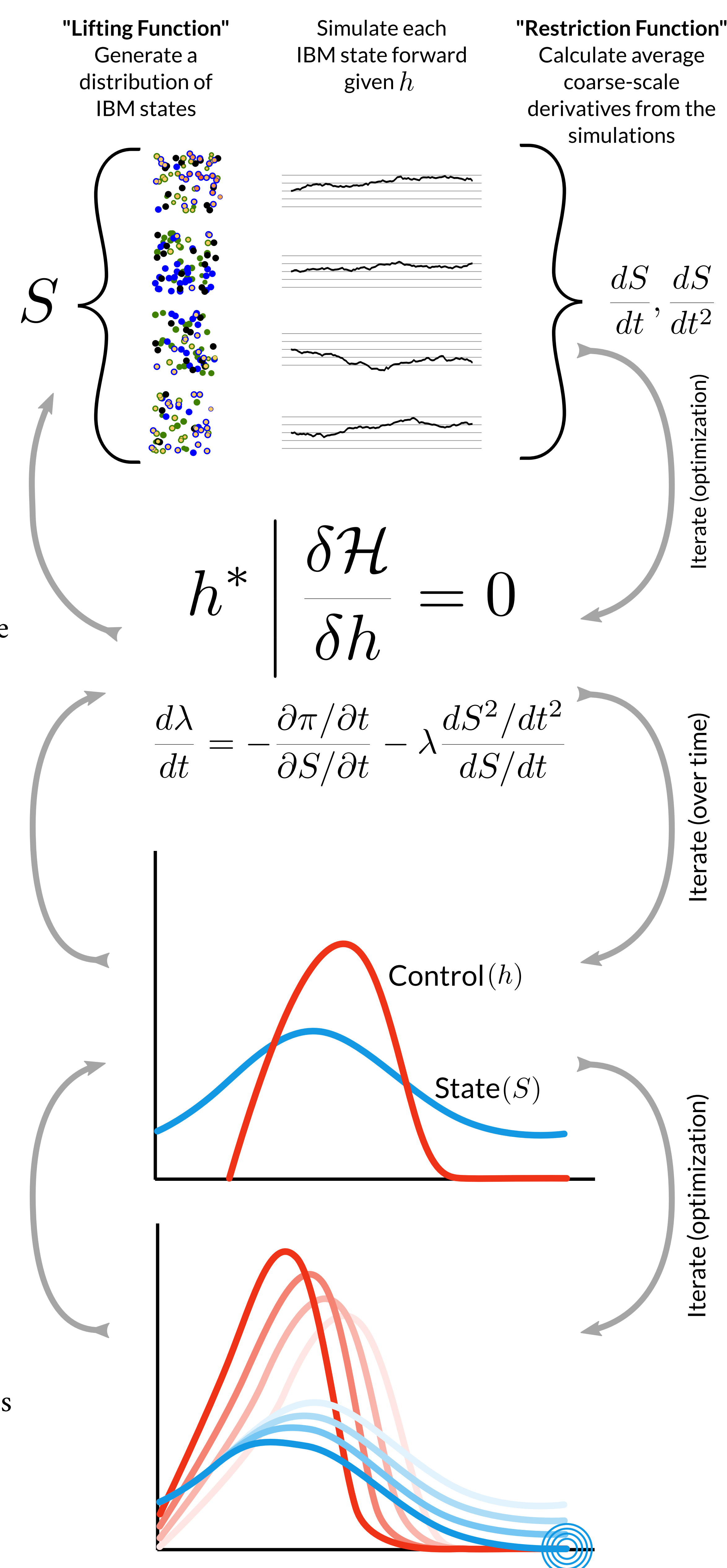
S = Population-scale variables, e.g. (infectious individuals)
 h = Control variable (e.g., rate of culling)
 π = Profit function
 λ = "Shadow value" of resource (contribution to future profits)
 t = Time

Create a **coarse stepper** to simulate the system by repeated simulations of the IBM. The stepper samples from possible IBM states generated from the coarse-scale system state, and runs the IBM using the control variable as a parameter.

Numerically optimize to find the control level (h) that maximizes the value of the system (\mathcal{H}) at time t . Use outputs of simulation with h^* to determine $d\lambda/dt$.

Advance in time by using the previous outputs to integrate and produce the optimal path of the control parameter, shadow values, and average system state.

Solve the **boundary value problem** by adjusting initial values to hit optimal final conditions.



Application: Thinning trees to slow disease spread

Property managers seek to conserve host tree populations under the threat of constant or increasing disease propagule pressure from the surrounding landscape. Culling or thinning to reduce disease must be balanced against loss of ecosystem services and threat of extinction of the host.

The optimization problem is to remove the correct number, size, species, and spatial configuration of trees to minimize host species loss from either disease, competition, or stochastic extinction. For this problem, I define the variables in the Hamiltonian equation as

S = A vector of susceptible trees, infected trees, and the spatial correlation between them that determines the infection rate. Trees are divided into sub-classes by size and species

h = The annual rate of tree harvest to suppress disease

π = The annual ecosystem service benefit provided by trees, minus the cost of harvest to suppress disease

λ = "Shadow value" of each variable, or how much each tree will contribute in future by continuing to provide services, and the future cost of cutting it down to prevent disease

t = Time


$f(S, h)$ = Change in tree populations over time, simulated by the IBM

Ongoing work

The methods described here are being developed as an R/C++ package, eqnfree, which also implements methods described in Kevrekidis and Samaey (2009).

Works Cited

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- Kevrekidis, I. G., and G. Samaey. 2009. Equation-free multiscale computation: algorithms and applications. *Annual review of physical chemistry* 60:321–44.

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