

# No Need for Excuses: Applying Software Engineering Principles to Facilitate Scientific Software Documentation



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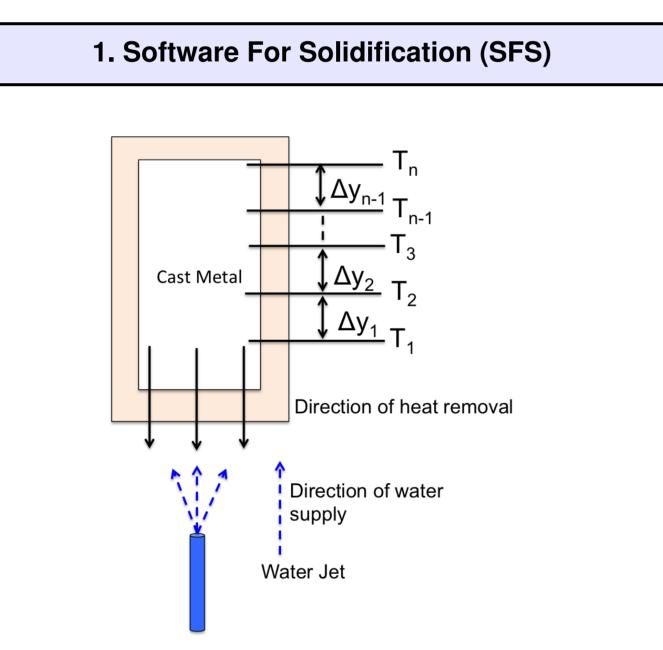
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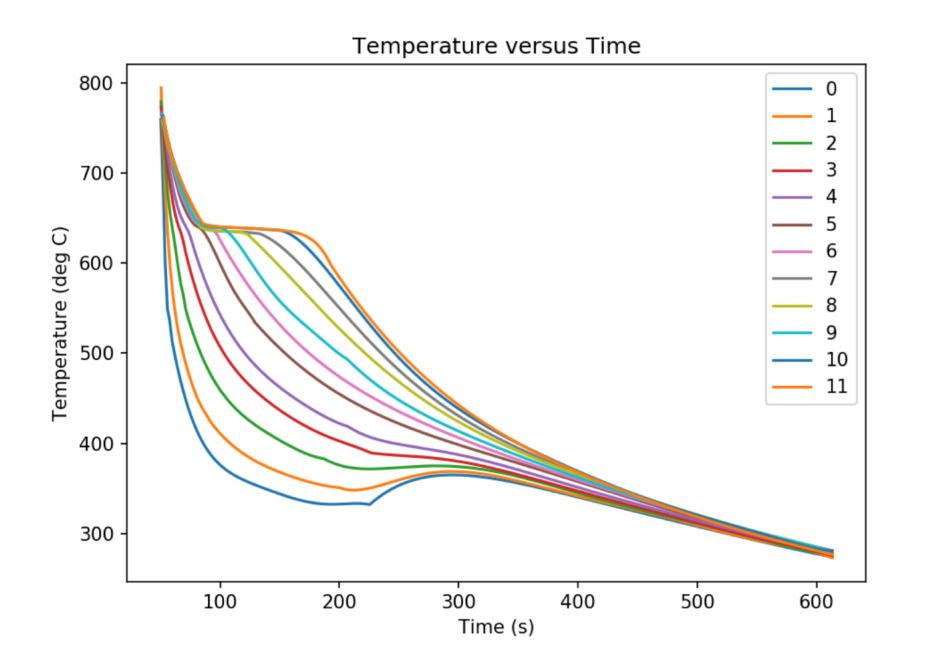
**S**OFTWARE documentation improves qualities such as maintainability, reusability, verifiability and usability. So why do scientific software developers underemphasize documentation? Reasons include: i) requirements are not known up-front (they emerge over time), ii) change is frequent, iii) rigid processes hamper creativity, iv) the software is too complex; and, v) there is no test oracle. These are reasons that documentation is challenging, *not excuses for avoiding it entirely*. Complexity and frequent change are not unique to scientific software. So how do other domains deal with these challenges – by applying Software Engineering (SE) principles, techniques and tools. Specific SE ideas helpful to scientific software include: faking a rational design process, documentation templates, abstraction, anticipation of change, generality, replicability, separation of concerns, information hiding, and tool support. Many developers are familiar with these ideas, but examples of adapting them to scientific software are rare. An example is shown here to illustrate SE ideas applied to software to analyze the solidification of a molten metal alloy.

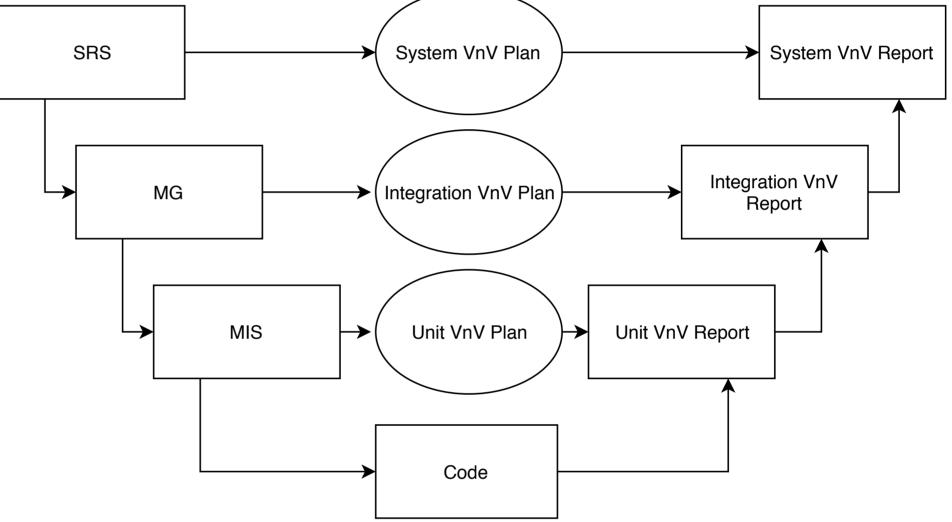
#### 2. Faking a Rational Design Process

A rational design process, with up-front requirements flowing into successive design stages, is not usually feasible, but the best way to write documentation is still to "fake" a rational process [2]. SFS was developed using a V-model, where a testing phase is associated with each step in the typical waterfall process. The documents include a Software Requirements Specification (SRS), a software architecture in a Module Guide (MG), and a detailed design in a Module Interface Specification (MIS) [3].









#### 3. Documentation Templates

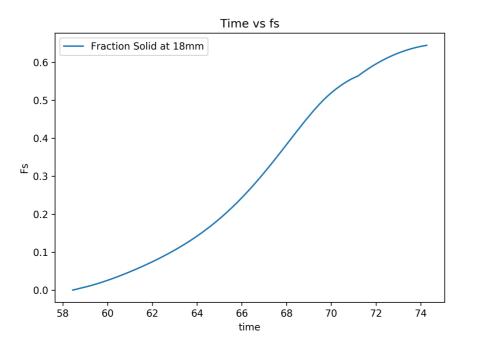
A template tailored to scientific software [5] was adopted for the SRS. The template was designed to use SE principles, like abstraction, separation of concerns, anticipation of change and generalization.

- 1. Reference Material: a) Table of Units b) Table of Symbols c) Abbreviations and Acronyms
- 2. Introduction: a) Purpose of Document b) Scope of Requirements c) Intended Audience d) Organization of Document
- 3. Background
- 4. General System Description: a) System Context b) User Characteristicsc) System Constraints
- 5. Specific System Description:

a) Problem Description: i) Terminology and Definitions ii) Physical System Description iii) Goal Statements

 b) Solution Characteristics Specification: i) Assumptions ii) Theoretical Models iii) General Definitions iv) Data Definitions v) Instance Models
 vi) Data Constraints vii) Properties of a Correct Solution

The output of SFS is the fraction solid ( $f_S$ ), either as a function of time, temperature or cooling rate.  $f_S$  is obtained by solving an Ordinary Differential Equation (ODE) based on the experimental temperature data (shown above), material properties and processing conditions [6].



#### 6. Requirements:

a) Functional Requirements: i) Configuration Mode ii) Calibration Mode iii) Calculation Mode

b) Non-Functional Requirements: i) Look and Feel Requirements ii) Usability and Humanity Requirements iii) Installability Requirements iv) Performance Requirements v) Operating and Environmental Requirements vi) Maintainability and Support Requirements vii) Security Requirements viii) Cultural Requirements ix) Compliance Requirements

7. Likely Changes

8. Unlikely Changes

9. Supporting Information

Templates designed using SE principles were also used for the Module Guide, Module Interface Specification, and the Verification and Validation plans and reports. The Python code mostly followed the PEP8 standard. Doxygen was used to generate documentation for the Application Program Interface (API).

# 4. Abstraction

The SRS for SFS starts with an abstract overall goal, which is later refined via general definitions to an instanced model, which is itself refined into a design and subsequently code.

For a given experiment with a metal alloy, using the thermocouple locations, temperature readings, material properties and initial conditions, SFS:

GS1: Computes the solid fraction  $(f_s)$  as a function of temperature (T) and cooling rate  $(f_s(T, \frac{dT}{dt}))$ .

The requirements for the SRS for SFS were stable throughout this development project because changeable design decisions were postponed via abstract requirements. For instance, the SRS does not specify whether the fit will use regression, interpolation, polynomials or some other basis functions.

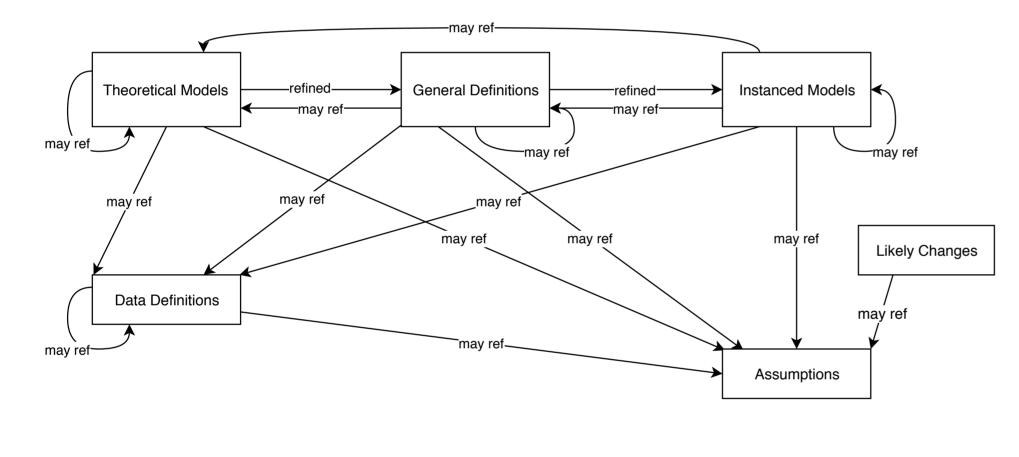
Number	GD4
Equation	$T(y,t) = \operatorname{fit}(Tdata, y_{TC}, dt) \text{ where } \operatorname{fit} : \mathbb{R}^{m \times n} \to \mathbb{R}^n \to \mathbb{R} \to (\mathbb{R} \to \mathbb{R})$
Descript.	Experimental temperature history data ( $Tdata$ ) at the thermocouples is used to determine the function $T(y, t)$ , where the inputs are $y$ (m), the position as measured from the bottom of the cylinder, and $t$ (second), the time. The output is the temperature (°C). fit() is a function that takes the thermocouple data $Tdata$ , the locations of the thermocouples $y_{TC}$ and the time step $dt$ , and returns the appropriate function $T(y,t)$ . $m$ is the number of instants of time where the thermocouple data is measured and $n$ is the number of thermocouples.

- A1: The only form of energy that is relevant for this problem is thermal energy. All other forms of energy, such as mechanical energy, are assumed to be negligible [T1, UC1].
- A2: The heat removal is assumed to be unidirectional and the heat conduction in axial direction is assumed to be 0 [GD1, UC2].
- A3: Heat transfer through the cylinder takes place by conduction only, not advection. [DD5].
- A4: We assume that  $C_v(T)$  can be expressed as a linear combination of the values at the beginning and at the end of solidification [IM4, DD1, GD2].
- A5: We assume that  $\alpha(T)$  can be expressed as a linear combination of the values at the beginning and at the end of solidification [IM4, DD2, GD2].
- A6: We assume that  $\rho(T)$  can be expressed as a linear combination of the values at the beginning and at the end of solidification [IM4, DD3, GD2].
- A7: Thermal conductivity through the liquid and solid metal is isotropic.
- A8: Newton's law of convective cooling applies between the water and the cast alloy [GD3, DD8].
- A9: The heat transfer coefficient at the bottom of the cylinder is assumed to be independent of temperature [GD3, LC1].
- A10: The thermal resistance due to the thermocouples is assumed to be negligible [GD4].
- A11: The cast metal is perfectly insulated by the sand mold so that there is no heat loss from the sand mold [GD1].
- A12: The density of the solidifying material is assumed to be constant for the derivation of  $\dot{f}_s$  [IM4].
- A13: The data collected from the thermocouples starts at time 0 and there is a constant time step between each data point [GD4, LC2].

# 8. Separation of Concerns

#### 5. Anticipation of Change

The SRS is designed with change in mind. The figure below shows the relationship between different parts of the requirements model. Cross-references are bi-directional. The traceability information is also summarized in a traceability matrix. A summary of likely changes is included in the SRS. Most likely changes are related to assumptions that may be modified in the future. Anticipation of change allows for creation of a family of related physical models.



#### 6. Generality

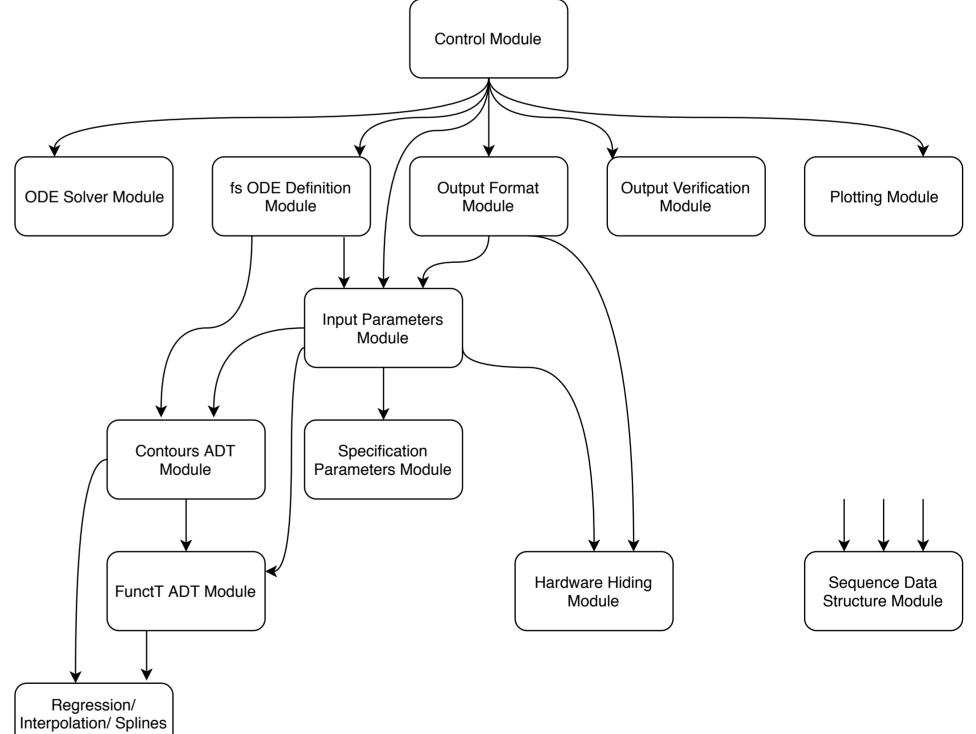
The instance model for solving  $f_S$  is written in the general ODE form, to take advantage of existing ODE solvers. Other research on solidification creates an unnecessary challenge by neglecting generality and instead developing its own ad hoc algorithms.

Number	IM4				
Input	$T(y,t)$ (see DD4), from which $\frac{\partial T}{\partial t}$ and $\frac{\partial^2 T}{\partial y^2}$ can be derived, as required				
	Material properties $C_v^L(T)$ , $C_v^S(T)$ , $\rho_L(T)$ , $\rho_S(T)$ , $\alpha_b$ (from IM2), $\alpha_e$ (from IM3), and $L$				
	$y^*$ , $(t_L, T_L)$ from DD6 and $(t_S, T_S)$ from DD7				
Output	Solve $f_s(t)$ at location $y^*$ such that the following ODE is satisfied with $f_s(t_L) = 0$ :				
$ \dot{f}_s(f_s, t) = \frac{C_v(f_s)}{L\rho(f_s)} \left[ \frac{\partial T(t)}{\partial t} - \alpha(f_s) \frac{\partial^2 T(t)}{\partial y^2} \right] $ where (derivation invokes simplifying assumptions)					

Properties of a correct solution can be brainstormed before a single line of code is written. The following property states that for any fixed time the temperature will be non-decreasing through the height of the cylinder.

Number	PC1
Equation	For any $t, t > 0$ , $(\forall y_1, y_2 : \mathbb{R}   0 \le y_1 \le H \land 0 \le y_2 \le H \land y_1 < y_2 : T_t(y_2) \ge T_t(y_1))$ where $T_t = \lambda y : T(y, t)$
Descript.	$T_t(y)$ is non-decreasing with increasing $y$ (the temperature rises (or remains the same) with increasing height in the cylinder).

The design is divided into modules, as shown in the following uses relationship.



# 7. Replicability

Although reproducibility is the cornerstone of the scientific method, until recently it has not been treated seriously in software [1]. To replicate the work of another, starting from the theory, requires full documentation of all relevant assumptions. Future change is anticipated via traceability to theories (T), unlikely changes (UC), likely changes (LC), general definitions (GD), data definitions (DD) and instance models (IM). Module

## 9. Information Hiding

The interface provides a constructor (new FunctT) that takes two vectors of data and returns a FunctT object. Accessors include minD and maxD for finding the extreme limits of the independent data variable. The accessor eval returns the value of the dependent variable (x), given a value for the independent variable (y). The syntax of FuncT shows exceptions if the data for the independent variable is not in ascending order, of if the number of data points in the two sequences do not match, or if a function evaluation is sought outside of the domain of the given data.

Routine	In	Out	Exceptions
new FunctT	$X_{in}:\mathbb{R}^n, Y_{in}:\mathbb{R}^n$	FunctT	IndepVarNotAscend,
			SeqSizeMismatch
minD		$\mathbb{R}$	
maxD		$\mathbb{R}$	
eval	$x:\mathbb{R}$	$\mathbb{R}$	OutOfDomain

The corresponding semantics for FunctT are given below.

# **State Variables**

 $\begin{array}{l} \mathsf{f} \colon \mathbb{R} \to \mathbb{R} \\ \mathsf{min}\mathsf{X} \colon \mathbb{R} \\ \mathsf{max}\mathsf{X} \colon \mathbb{R} \end{array}$ 

new FunctT( $X_{in}, Y_{in}$ ):

• transition: minX, maxX,  $f := X_0, X_{|X|-1}, (\lambda v : interp(X, Y, v))$ 

```
• output: out := self
```

• exception:  $exc := (\neg isAscending(X_{in}) \Rightarrow IndepVarNotAscend| |X_{in}| \neq |Y_{in}| \Rightarrow SeqSizeMismatch)$ 

# minD():

```
• output: out := minX
```

```
• exception: None
```

#### ... eval(*x*):

• output: out := f(x)

• exception:  $exc := (\neg(\min X \le x \le \max X) \Rightarrow OutOfDomain)$ 

# **Local Functions**

interp:  $\mathbb{R}^n \times \mathbb{R}^n \times \mathbb{R} \to \mathbb{R}$ interp(X, Y, v)

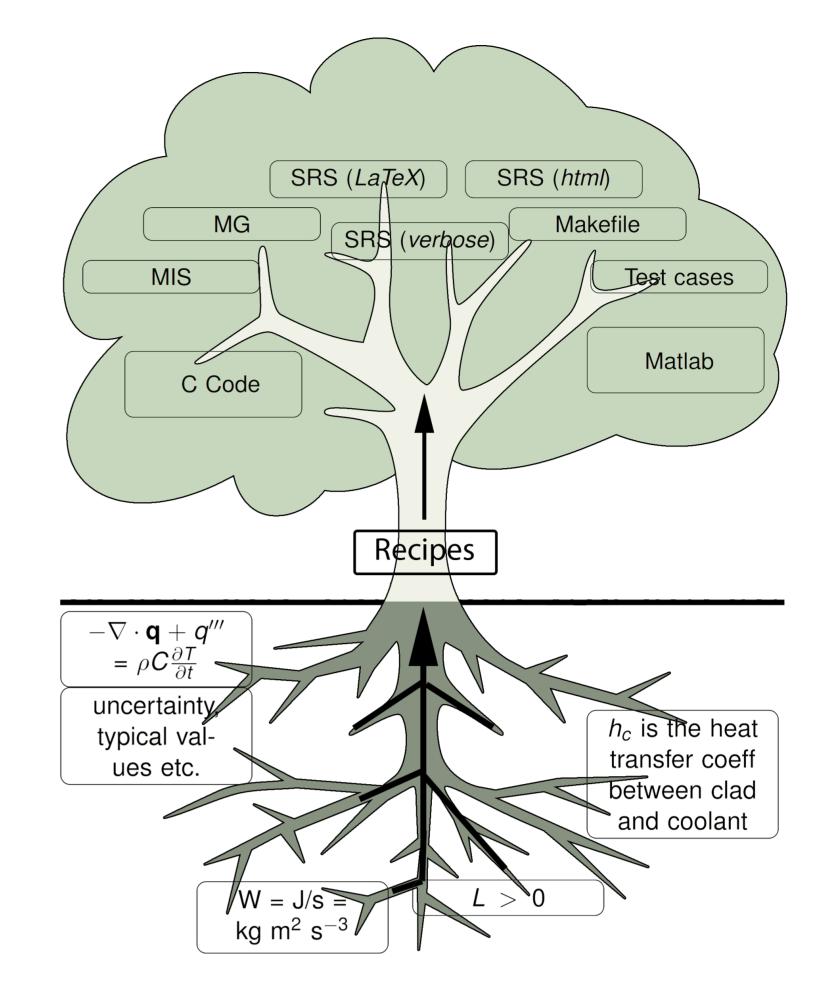
```
\equiv interpQuad(X_{i-1}, Y_{i-1}, X_i, Y_i, X_{i+1}, Y_{i+1}, v) where i = index(X, v)
```

```
interpQuad: \mathbb{R} \times \mathbb{R} \times \mathbb{R} \times \mathbb{R} \times \mathbb{R} \times \mathbb{R} \times \mathbb{R} \to \mathbb{R}
interpQuad(x_0, y_0, x_1, y_1, x_2, y_2, x)
```

$$\equiv y_1 + \frac{y_2 - y_0}{x_2 - x_0} (x - x_1) + \frac{y_2 - 2y_1 + y_0}{2(x_2 - x_1)^2} (x - x_1)^2$$

# 10. Tool Support

Ideally, the documentation can be generated as different views of the scientific, computing and documentation knowledge [7].



index:  $\mathbb{R}^n \times \mathbb{R} \to \mathbb{N}$  # constructor test ensures sequence is ascending index(X, x)  $\equiv i$  such that  $X_i \leq x < X_{i+1}$ 

Below we show the syntax and semantics for the MIS for ContourADT. The full data set is built up by adding each successive thermocouple's data. The accessors, eval, dydx and d2ydx2 are used to calculate the values of T(y,t),  $\frac{\partial T}{\partial t}$  and  $\frac{\partial^2 T}{\partial y^2}$ , respectively. The access program slice returns a new FuncT that would hold the temperature values through the height of the cylinder for a given value of the dependent variable t. The interfaces for FunctT and ContoursT are stable with respect to changes in the fitting algorithm or basis functions.

Routine	In	Out	Exceptions
ContoursT			
add	s: FunctT,		IndepVarNotAscend
	$z:\mathbb{R}$		
getC	$i:\mathbb{N}$		InvalidIndex
eval	$x:\mathbb{R}, z:\mathbb{R}$		OutOfDomain
dydx	$x:\mathbb{R}, z:\mathbb{R}$		OutOfDomain
d2ydx2	$x:\mathbb{R}, z:\mathbb{R}$		OutOfDomain
slice	$x:\mathbb{R}$	FunctT	

# Semantics: State Variables

S: sequence of FunctT

Z: sequence of  $\mathbb R$ 

new ContoursT(i):

• transition: S, Z := <>, <>

• exception: none

# add(*s*, *z*):

- transition: S, Z := S|| < s >, Z|| < z >
- exception:  $exc := (|Z| > 0 \land z < Z_{|Z|-1} \Rightarrow \mathsf{IndepVarNotAscend})$

# 11. Conclusions

 $\mathbf{N}^{\circ}$  more excuses! Documentation of requirements, design, code and tests cases is not easy, but it is feasible. The long-term reliability, replicability, reusability and maintainability of scientific software depends on documentation. The following ideas from SE facilitate high quality documentation that is flexible to change:

- Faking a rational design process Documentation templates
- Abstraction
- Generality
- Separation of concerns
- Anticipation of change
- Replicability
- Information hiding

In the future, increasing tool support will enable documentation that is complete, consistent and traceable by construction [4].

# Acknowledgements

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getC(i):

• output: out := S[i]

• exception:  $exc := (\neg (0 \le i < |S|) \Rightarrow \text{InvalidIndex})$ 

eval(x, z):

• output: out := self.slice(x).eval(z)

• exception: none

dydx(x, z):

• output:  $out := \frac{eval(x + \Delta x, z) - eval(x, z)}{\Delta x} \# \Delta x$  is a defined constant • exception:  $exc := (\neg Z_0 \le z \le Z_{|Z|-1} \Rightarrow OutOfDomain)$ 

... ....

slice(x):

```
• output: out := \operatorname{FunctT}(Z, \langle S_0.\operatorname{eval}(x), ..., S_{|S|-1}.\operatorname{eval}(x) \rangle)
```

• exception: None

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