



On the discretization of vertical diffusion in the turbulent surface and planetary boundary layers

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Context: representation of mixing in PBLs

Proof Reynolds averaging $(\phi = \langle \phi \rangle + \phi')$

$$\partial_t \langle \phi \rangle = \ldots + \operatorname{div}(\langle \mathbf{u}' \phi' \rangle) + \ldots$$

- Diffusive approach for "local" mixing (K-theory)
 - ⇒ Boundary layer approximations: horiz, homogeneity and eddy diffusion

$$\langle w'\phi' \rangle = -K\partial_z \langle \phi \rangle$$

$$\langle w'\phi' \rangle = -K\partial_z \langle \phi \rangle \qquad \rightarrow \qquad \partial_t \langle \phi \rangle = \ldots + \frac{\partial_z (K\partial_z \langle \phi \rangle)}{\partial_z \langle \phi \rangle} + \ldots$$

- → Down-gradient fluxes
- → Turbulence acts as a "mixing"
- Mass flux approach for "non-local" mixing (e.g. Chatfield & Brost, 1987; Siebesma, 2007)



$$\left\langle w'\phi'\right\rangle = -K\partial_z\left\langle \phi\right\rangle + \alpha w_u(\phi_u - \left\langle \phi\right\rangle) \quad \rightarrow \quad \partial_t\left\langle \phi\right\rangle = \partial_z(K\partial_z\left\langle \phi\right\rangle) - \partial_z(\alpha w_u\left\langle \phi\right\rangle) + \dots$$

⇒ advection-diffusion operator to parametrize unresolved scales in PBLs and beyond (e.g. internal wave breaking or convective adjustment)

Context: representation of mixing in PBLs

Standard schemes to provide K:

- 0-equation: algebraic computation of the eddy parameters from bulk properties
- 1-equation: prog. eqn for turbulent kinetic energy (TKE) + diagnostic mixing length
- 2-equations: prog. eqn for TKE and for a "generic" length scale $(\epsilon, \omega, ...)$

The resulting turbulent viscosity/diffusivity K

- ightarrow strongly varies spatially (internal & boundary layers), i.e. large values of $\frac{h(\partial_z K)}{K}$
- → depends nonlinearly on model variables
- ightarrow induces stiffness i.e. large vertical parabolic Courant numbers $\sigma^{(2)}=\frac{K\Delta t}{h^2}$

Usual approach (e.g. WRF, LMDZ, all oceanic models):

use of (semi)-implicit temporal schemes with 2nd-order FD discretization

Context: standard approach

- What could be wrong with second-order scheme in space?
 - Nothing . . . if pure diffusion (i.e. with constant *K*) is considered

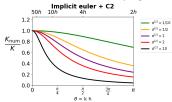
$$\partial_z \left(K \partial_z \phi \right)_k^{(\mathrm{C2})} = \partial_z (K \partial_z \phi)_k + \frac{h^2}{12} \left\{ K \partial_z^4 \phi \right\} + \mathcal{O}(\Delta z^4)$$

 $\begin{array}{l} \cdot \text{ but with } \mathrm{Pe}^{(n)} = \frac{h^n \partial_x^u K}{K} \neq 0, \ n \geq 1 \\ \partial_z \left(K \partial_z \phi \right)_k^{\mathrm{C2}} = \partial_z (K \partial_z \phi)_k + \frac{1}{24} \partial_z \left(K \left[\mathrm{Pe}^{(2)} \partial_z \phi + 2 \varDelta z \mathrm{Pe}^{(1)} \partial_z^2 \phi + 2 \varDelta z^2 \partial_z^3 \phi \right] \right) + \mathcal{O}(\varDelta z^4) \end{array}$

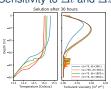
- What could be wrong with (semi)-implicit scheme in time?
 - Lack of monotonic damping (e.g. Manfredi & Ottaviani, 1999; Wood et al., 2007)
 possibly leaving noise uncontrolled (+ trigger conv. adjust.)
 - Inexact damping for large $\sigma^{(2)}$
 - $\mathcal{O}(\Delta t)$ errors in coupling with physical parameterizations

Impact on model solutions

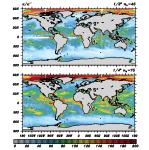
numerical vs exact damping rate



Sensitivity to Δt and Δz



Single-column exp. (Wind-induced deepening of BL)



Maps of K/K^{num} from oceanic realistic simulations

- K^{num} is the diffusivity in the continuous equation with same damping as the numerical damping
- $K/K^{\mathrm{num}}\gg 1 \Rightarrow$ the damping seen by the model is smaller than the theoretical damping.

•
$$\sigma^{(2)} = \overline{\sigma^{\text{mld}}}, \, \theta = \frac{2\pi}{N_{\text{mld}}}.$$

Objectives

- Have a better control of numerical sources of error independently from the physical principles of the subgrid scheme
- ightharpoonup Consistency between the parameterizations and the resolved fluid dynamics (for bottom boundary condition & K(z) computation)

Outline

- 1. Spatial discretization
- 2. Treatment of the bottom boundary condition (MO consistency)
- 3. Combination with time discretization
- 4. Combination with subgrid closure schemes

Spatial discretization

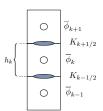
Objectives & motivations

Constraints

- · limit ourselves to tridiagonal linear problems
- possibility to have a joint treatment of vertical advection and diffusion
- allow a finite-volume interpretation

Possible alternatives

- Exponential Compact scheme (e.g.McKinnon & Johnson, 1991; Tian & Dai, 2007)
 - ightarrow Specifically designed for accuracy with large Peclet numbers
- Padé compact finite volume discretization



General form of the discretization

$$\partial_z(K\partial_z\phi) = \frac{K_{k+1/2}d_{k+1/2} - K_{k-1/2}d_{k-1/2}}{h_{k+1/2}}, \qquad d_{k+1/2} = (\partial_z\phi)_{k+1/2}$$

for standard discretization: $d_{k+1/2} = (\phi_{k+1} - \phi_k)/h$ (h : vertical layers thickness)

Parabolic splines reconstruction

Suppose a given set of $\{\overline{\phi}_k, k=1,\ldots,N\}$ and assume a subgrid parabolic reconstruction

$$\phi(\xi) = a\xi^2 + b\xi + c, \qquad \xi \in \left] -\frac{h_k}{2}, \frac{h_k}{2} \right[$$

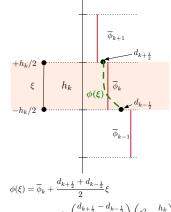
under the constraints

•
$$\frac{1}{h_k} \int_{-\frac{h_k}{2}}^{\frac{h_k}{2}} \phi(\xi) d\xi = \overline{\phi}_k$$

•
$$\partial_z \phi(+h_k/2) = d_{k+1/2}, \, \partial_z \phi(-h_k/2) = d_{k-1/2}$$

+ Impose the continuity of ϕ at cell interfaces :

$$\frac{1}{6} d_{k+3/2} + \frac{2}{3} d_{k+1/2} + \frac{1}{6} d_{k-1/2} = \frac{\overline{\phi}_{k+1} - \overline{\phi}_k}{h}$$



$$\begin{split} \phi(\xi) &= \overline{\phi}_k + \frac{a_{k+\frac{1}{2}} + a_{k-\frac{1}{2}}}{2} \xi \\ &\quad + \left(\frac{d_{k+\frac{1}{2}} - d_{k-\frac{1}{2}}}{2h_k}\right) \left(\xi^2 - \frac{h_k}{12}\right) \end{split}$$

- necessitates inversion of an implicit linear system of equations
- compact accuracy (4th-order for advection, 2nd for diffusion)
- Widely used for vertical advection in oceanic models

Compact Padé Finite Volume methods

Lele, 1992; Kobayashi, 1999

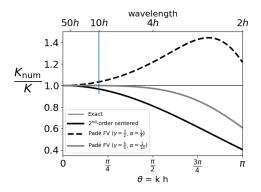
Unknowns : derivatives $d_{k+\frac{1}{2}}$ on cell interfaces, for $m,n\in\mathcal{N}$

$$\sum_{i=1}^{m} \alpha_{i} \boldsymbol{d_{k+\frac{1}{2}-i}} + \boldsymbol{d_{k+\frac{1}{2}}} + \sum_{i=1}^{m} \alpha_{i} \boldsymbol{d_{k+\frac{1}{2}+i}} = \frac{1}{h} \left(\sum_{j=1}^{n} \gamma_{j} \overline{\phi}_{k+j} - \sum_{j=1}^{n} \gamma_{j} \overline{\phi}_{k-j+1} \right)$$

$$\begin{split} \bullet \ \ \text{For} \ (m,n) &= (1,1): \alpha_1 d_{k-\frac{1}{2}} + d_{k+\frac{1}{2}} + \alpha_1 d_{k+\frac{3}{2}} = \gamma_1 \left(\frac{\phi_{k+1} - \phi_k}{h} \right) \\ &(\alpha_1,\gamma_1) = \left(\frac{1}{10},\frac{6}{5} \right) \qquad \rightarrow \text{4th-order discretization of } d_{k+\frac{1}{2}} \ \text{(for } K = \text{cste)} \\ &(\alpha_1,\gamma_1) = \left(\frac{1}{4},\frac{3}{2} \right) \qquad \rightarrow \text{equivalent to parabolic splines reconstruction.} \end{split}$$

- · Can be reinterpreted in terms of subgrid reconstruction as parabolic splines
- Flexibility provided by α and γ parameters

Effective viscosity/diffusivity

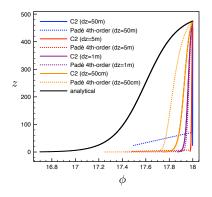


- · Illustration: stationary problem

$$\begin{cases} \partial_z \left(K(z) \partial_z \phi \right) &=& \frac{\partial_z \mathcal{R}}{\rho C_p} \\ \phi(0) &=& \phi_{\text{bot}} \\ \phi\left(\frac{19h_{\text{bl}}}{20} \right) &=& \phi_{\text{top}} \end{cases}$$

with

$$K(z) = \kappa \phi_{\star} \frac{z}{h_{\rm bl}} (h_{\rm bl} - z) + K_{\rm mol}$$
$$\mathcal{R}(z) = \mathcal{R}_0 \left(\alpha e^{-z/\zeta_0} + (1 - \alpha) e^{-z/\zeta_1} \right)$$

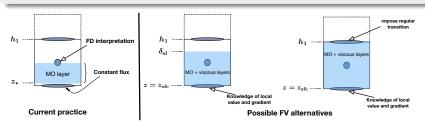


2

Treatment of the bottom boundary condition (MO consistency)

Treatment of boundary cells (neutral case)

Dirichlet boundary condition is never applied in practice → replaced by a flux condition consistent with wall laws



Current practice:

$$\begin{cases} \partial_z \left(\kappa |\phi_{\star}| (z + z_{\star}) \partial_z \phi \right) &= 0 \\ \phi(z_{\star}) &= \chi_{\text{sfc}} \\ \phi(h_1/2) &= \phi_1 \end{cases}$$

$$\phi(z) = (\phi_1 - \chi_{\rm sfc}) \left(\frac{\ln\left(\frac{1}{2} + \frac{z}{2z_{\star}}\right)}{\ln\left(\frac{1}{2} + \frac{h_1}{4z_{\star}}\right)} \right) + \chi_{\rm sfc}$$

FV approach with $h_1 = \delta_{\rm sl}$:

$$\left\{ \begin{array}{cccc} \partial_z \left(\kappa | \phi_\star | (z+z_\star) \partial_z \phi \right) & = & 0 \\ \phi(z_\star) & = & \chi_{\rm sfc} \\ \phi(h_1/2) & = & \phi_1 \end{array} \right. \quad \left\{ \begin{array}{cccc} \partial_z \left(\kappa | \phi_\star | (z+z_\star) \partial_z \phi \right) & = & 0 \\ \phi(z_{\rm sfc}) & = & \chi_{\rm sfc} \\ \phi(h_1) & = & \phi_{3/2} \end{array} \right.$$

$$\phi(z) = (\phi_1 - \chi_{\rm sfc}) \left(\frac{\ln\left(\frac{1}{2} + \frac{z}{2z_{\star}}\right)}{\ln\left(\frac{1}{2} + \frac{h_1}{4z_{\star}}\right)} \right) + \chi_{\rm sfc} \qquad \phi(z) = (\phi_{3/2} - \chi_{\rm sfc}) \left(\frac{\ln\left(1 + \frac{z}{z_{\star}}\right)}{\ln\left(1 + \frac{h_1}{z_{\star}}\right)} \right) + \chi_{\rm sfc}$$

Treatment of boundary cells with Parabolic splines

2nd-order polynomial subgrid reconstruction for $z \in]-\frac{h_k}{2}, \frac{h_k}{2}[$:

$$\phi(z) = \overline{\phi}_k + \left(\frac{d_{k+1/2} + d_{k-1/2}}{2}\right)z + \frac{d_{k+1/2} - d_{k-1/2}}{2h_k} \ \left(z^2 - \frac{h_k}{12}\right)$$

Usual treatment of boundary cell (with Dirichlet B.C.)

$$\phi\left(-\frac{h_1}{2}\right) = \overline{\phi}_1 - \frac{h_1}{3}d_{1/2} - \frac{h_1}{6}d_{3/2} = \chi_{\rm sfc} \quad \to \frac{1}{3}d_{1/2} + \frac{1}{6}d_{3/2} = \frac{\overline{\phi}_1 - \chi_{\rm sfc}}{h_1}$$



Alternative treatment

$$\phi(z) = (\phi_{3/2} - \chi_{\rm sfc}) \left(\frac{\ln\left(1 + \frac{z}{z_{\star}}\right)}{\ln\left(1 + \frac{h_1}{z_{\star}}\right)} \right) + \chi_{\rm sfc} = d_{3/2}(h_1 + z^{\star}) \ln\left(1 + \frac{z}{z_{\star}}\right) + \chi_{\rm sfc}$$

$$\rightarrow d_{1/2} = d_{3/2} \left(1 + \frac{h}{z_+} \right)$$
 (consistant with constant flux layer)

$$\rightarrow \ \frac{1}{6}d_{5/2} + \left[\frac{1}{3} + \left(1 + \frac{z_\star}{h}\right)\ln\left(1 + \frac{h}{z_\star}\right)\right]d_{3/2} = \frac{\overline{\phi}_2 - \chi_{\rm sfc}}{h} \ \text{(impose regularity)}$$

Treatment of boundary cells with Parabolic splines

Asymptotics:

Resolved case (combining the first 2 lines of the matrix)

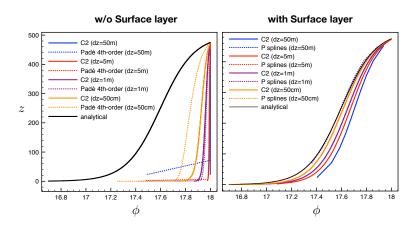
$$\frac{1}{6}d_{5/2} + \frac{5}{6}d_{3/2} + \frac{1}{2}d_{1/2} = \frac{\overline{\phi}_2 - \chi_{\text{sfc}}}{h}$$

Unresolved case (for $h \to 0$)

$$\frac{1}{6}d_{5/2} + \underbrace{\left(\frac{1}{3} + \left[1 + \frac{h}{2z_{\star}}\right]\right)d_{3/2}}_{\frac{5}{6}d_{3/2} + \frac{1}{2}d_{1/2}} = \frac{\overline{\phi}_2 - \chi_{\text{sfc}}}{h}$$

Smooth transition between the unresolved and the resolved limit.

A numerical example (with $z_{\star} = K_{\mathrm{mol}}/(\kappa |\phi_{\star}|)$)



3

Combination with time discretization

Combination with implicit time discretization

Combine Padé-type schemes with implicit Euler:

$$\begin{cases} \alpha d_{k+3/2}^{n+1} + d_{k+1/2}^{n+1} + \alpha d_{k-1/2}^{n+1} = \gamma \frac{\overline{\phi}_{k+1}^{n+1} - \overline{\phi}_{k}^{n+1}}{h} \\ \overline{\phi}_{k}^{n+1} = \overline{\phi}_{k}^{n} + \frac{\Delta t}{h} \left[K_{k+1/2} d_{k+1/2}^{n+1} - K_{k-1/2} d_{k-1/2}^{n+1} \right] + \Delta t \operatorname{rhs}_{k} \\ \overline{\phi}_{k+1}^{n+1} = \overline{\phi}_{k+1}^{n} + \frac{\Delta t}{h} \left[K_{k+3/2} d_{k+3/2}^{n+1} - K_{k+1/2} d_{k+1/2}^{n+1} \right] + \Delta t \operatorname{rhs}_{k+1} \end{cases}$$

to end up with the following single tridiagonal problem

$$\begin{split} \left(\frac{\alpha}{\gamma} - \frac{K_{k+3/2}\Delta t}{h^2}\right) d_{k+3/2}^{n+1} &+ \left(\frac{1}{\gamma} + 2\frac{K_{k+1/2}\Delta t}{h^2}\right) d_{k+1/2}^{n+1} + \left(\frac{\alpha}{\gamma} - \frac{K_{k-1/2}\Delta t}{h^2}\right) d_{k-1/2}^{n+1} \\ &= \frac{\overline{\phi}_{k+1}^n - \overline{\phi}_k^n}{h} + \frac{\Delta t}{h} (\mathrm{rhs}_{k+1} - \mathrm{rhs}_k) \end{split}$$

- · easy to generalize for non-constant grid-size
- The tridiagonal solve provides the flux and not $\overline{\phi}$

Relevant properties for a well-behaved numerical solution

(e.g. Manfredi & Ottaviani (1999); Wood et al. (2007))

- Unconditional stability
- Monotonic damping (damping increases with increasing wavenumber, i.e. $\partial_{\theta} A < 0$)
- Non-oscillatory (i.e. $A \ge 0$)
- Proper control of grid-scale noise $\forall \sigma^{(2)}$
- → Convergence & stability are often not sufficient

Existing alternatives:

- Crank-Nicolson: ill-behaved for large time-steps
 → short wave-lengths not damped efficiently
- 2. 2nd-order "Padé" 2-step scheme (e.g Manfredi & Ottaviani 1999; Wood et al. 2007) :

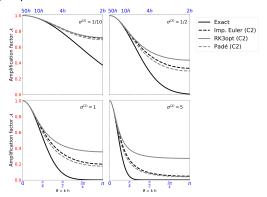
$$\begin{cases} (1+a(K\Delta t)\widetilde{k}^2)\phi^{\star} &= (1+b(K\Delta t)\widetilde{k}^2)\phi^n \\ (1+b(K\Delta t)\widetilde{k}^2)\phi^{n+1} &= \phi^{\star} \end{cases} \qquad \begin{array}{ccc} a &= 1+\sqrt{2}, \\ b &= 1+1/\sqrt{2} \end{cases}$$

3. Diagonally-implicit RK (e.g Nazari et al., (2013,2014))

$$\begin{cases} \phi^{(1)} &= \phi^n + (K\Delta t)\tilde{k}^2 a_{11}\phi^{(1)} \\ \phi^{(2)} &= \phi^n + (K\Delta t)\tilde{k}^2 (a_{21}\phi^{(1)} + a_{22}\phi^{(2)}) \\ \phi^{(3)} &= \phi^n + (K\Delta t)\tilde{k}^2 (a_{31}\phi^{(1)} + a_{32}\phi^{(2)} + a_{33}\phi^{(3)}) \\ \phi^{n+1} &= \phi^n + (K\Delta t)\tilde{k}^2 (b_1\phi^{(1)} + b_2\phi^{(2)} + b_3\phi^{(3)}) \end{cases}$$

Existing alternatives:

- 2. 2nd-order two-step scheme
- 3. Diagonally-implicit RK



Preserves qualitatively the features of the original equation

Temporal discretization with FV Padé scheme

Illustration with implicit Euler scheme :

$$\mathcal{A}(\sigma^{(2)}, \theta) = \frac{1 + 2\alpha \cos \theta}{1 + 2\alpha \cos \theta + 4\gamma \sigma^{(2)} (\sin \frac{\theta}{2})^2}$$

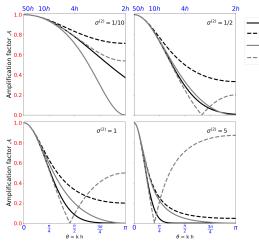
- 2nd-order accurate in space : $\alpha = \frac{\gamma 1}{2}$
- $\forall \gamma \neq 0, \, \partial_{\theta} \mathcal{A} < 0 \, \rightarrow \, \text{non-oscillatory if } \mathcal{A}(\sigma^{(2)}, \pi) \geq 0$
- · Two possibilities:

$$\mathcal{A}(\sigma^{(2)},\pi) = 0 \rightarrow \gamma = 2$$

$$\mathcal{A} = \frac{1}{1 + 4\sigma^{(2)}\sin(\theta/2)^2}$$

Implicit Euler + Padé FV (
$$\gamma = 2, \alpha = 1/2$$
)

$$A = \frac{1}{1 + 4\sigma^{(2)}\tan(\theta/2)^2}$$

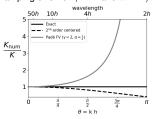


→ Padé FV scheme provides flexibility in the spatial discretization to counteract time discretization errors.



Exact Imp. Euler (C2)

Imp. Euler $(\gamma = 2, \alpha = \frac{1}{2})$ Imp. Euler (2.4)



4

Combination with subgrid closure schemes

Mathematical stability of closure models (e.g. Deleersnijder et al., 2009)

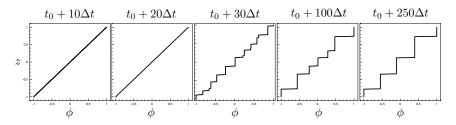
• An example : analogy with a local Ri-dependent model

$$\partial_t \phi = \partial_z \left(K(z) \partial_z \phi \right), \qquad K(z) = (\partial_z \phi)^{-2}$$

- $\triangleright K(z) > 0 \rightarrow \phi$ remains bounded
- Original equation can be reexpressed as

$$\partial_t (\partial_z \phi) = \partial_z \left(\widetilde{K}(z) \partial_z (\partial_z \phi) \right), \qquad \widetilde{K}(z) = -(\partial_z \phi)^{-2}$$

- \rightarrow the gradient can grow unbounded
- Numerical test : $\phi(z, t = 0) = z$, $\phi(z = -1, t) = -1$, $\phi(z = 1, t) = 1$



Mathematical stability of closure models (e.g. Deleersnijder et al., 2009)

An example : analogy with a local Ri-dependent model

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 \rightarrow the gradient can grow unbounded

- Ill-behaved solution due to the continuous formulation of the closure model and not to the details of its numerical discretisation
 - \rightarrow 0-equation closures are hard to study since it can change the diffusive nature of the equation
- More generally, spurious oscillations generally noticed are of a mathematical or a numerical nature?

Energetic consistency – mixing terms vs turbulent closure

For X-equation closures with X>0 a global energy budget can be derived

$$\begin{array}{llll} \partial_{t}u-\partial_{z}\left(K_{m}\partial_{z}u\right) & = & 0 \\ \partial_{t}b-\partial_{z}\left(K_{s}\partial_{z}b\right) & = & 0 \end{array} \rightarrow \begin{array}{lll} \partial_{t}\mathrm{KE}-\partial_{z}\left(K_{m}\partial_{z}\mathrm{KE}\right) & = & -K_{m}\left(\partial_{z}u\right)^{2} & = -P \\ \partial_{t}\mathrm{PE}-\partial_{z}\left((-z)K_{s}\partial_{z}b\right) & = & K_{s} & \partial_{z}b & = -B \end{array}$$

$$\partial_t \text{TKE} - \partial_z (K_e \partial_z \text{TKE}) = P + B - \varepsilon$$

Energy budget in a water column (ignoring the contribution of B.C.):

$$E = \int_{z_{\mathrm{hot}}}^{z_{\mathrm{top}}} (\mathrm{KE} + \mathrm{PE} + \mathrm{TKE}) dz \qquad \rightarrow \qquad \partial_t E = -\int_{z_{\mathrm{hot}}}^{z_{\mathrm{top}}} \varepsilon dz$$

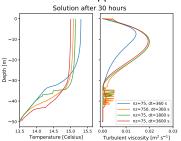
 The discrete counterpart of it tells you exactly how to discretize forcing terms in the TKE equation

Wind-induced deepening of boundary layer

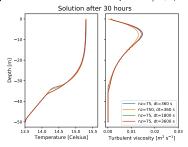
Kato & Phillips: On the penetration of a turbulent layer into stratified fluid, J. Fluid Mech., 1969 Price: On the scaling of stress-driven entrainment experiments, J. Fluid Mech., 1979

- Single column experiments with 0-equation closure (KPP, Large et al., 1994)
 - Use subgrid reconstruction to detect critical Ri-number
 - "Energy consistent" discretization of the Richardson number

Standard approach



Implicit Euler + FV Padé ($\alpha = 1/2, \gamma = 2$)



Summary

- Padé FV approach provides a good combination of simplicity and flexibility to handle diffusive terms with minimal changes in existing codes
 - Allows a good combination with surface layer param. and existing time-stepping
 - Provides degrees of freedom to mitigate numerical errors in time or to impose desired properties
- Simple single column test (Kato & Phillips) indicates a reduced sensitivity to numerical parameters

Perspectives

- Nonlinear stability (inputs on known pathological behaviors are welcome)
- Bottom boundary condition
 - Neutral case → stratified case
- Single column tests & global ocean simulation within NEMO
- Add representation of oceanic molecular sublayer + MO layer in the top most oceanic grid box for OA coupling purposes (e.g. Zeng & Beljaars, 2005)