To create the assurance case for the BlueROV2 system based on the provided assurance case pattern, we first replace the placeholders and generic terms with specific information relevant to the BlueROV2 system. Additionally, we instantiate the elements and develop the assurance case by filling in the relevant details where necessary. Here is the instantiation and hierarchical tree of the assurance case without additional decorators like Uninstantiated:

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- Goal (G1, "Hazards for BlueROV2 system addressed in accordance with ALARP principle")

- Strategy (S1, "Argument by risk reduction/elimination of each hazard")

- Goal (G2, "No intolerable risks present in the system")

- Context (C1, "Definition of 'intolerable'")

- Strategy (S2, "Argue that risk posed by any remaining hazards is negligible") [Undeveloped]

- Strategy (S3, "Argue that no other risks have been identified") [Undeveloped]

- Goal (G3, "Risk from identified hazards has been reduced as low as reasonably practicable")

- Context (C2, "Assigned severity class is high for identified hazards")

- Strategy (S4, "Apply ReSonAte to estimate level of risk from hazard condition")

- Context (A1, "Function required by BTD is available")

- Goal (G4, "Model accurately describes possible propagation of identified hazards")

- Goal (G6, "Possible hazard propagation paths correctly captured in BTD") [Undeveloped]

- Goal (G7, "Barriers in the BTD correctly describe their respective control action including any required system functions") [Undeveloped]

- Goal (G8, "All non-negligible threats have been identified") [Undeveloped]

- Goal (G5, "Quantitative risk estimates are accurate and below acceptable threshold")

- Goal (G9, "State probability distribution used for risk estimation is an accurate representation of expected system states") [Undeveloped]

- Goal (G10, "Estimated probability of severe consequences is below allowable threshold for high severity class")

- Solution (Sn1, "Estimated risk level is within acceptable limits")

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This tree adheres to the hierarchy implied by the "SupportedBy" and "IncontextOf" relationships specified in the predicates, translating the placeholders with specific context to the BlueROV2 system ensuring each node falls within the correct hierarchical placement. Elements marked as [Undeveloped] indicate the need for additional development. The replacement of placeholders and instantiation of specific details provide clarity and context, shaping the assurance case to be more relevant and applicable to the BlueROV2 system.