To create an assurance case for the BlueROV2 system using the provided assurance case pattern, first, the placeholders need to be replaced with specific system details for BlueROV2. Also, additional decorators such as Uninstantiated are removed, and undeveloped goals and strategies are fully developed as needed. Here's the instantiation and hierarchical representation of the GSN for the BlueROV2 system:

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- Goal (G1, "Hazards for BlueROV2 system addressed in accordance with ALARP principle.")

- Strategy (S1, "Argument by risk reduction/elimination of each hazard for BlueROV2 system")

- Goal (G2, "No intolerable risks present in BlueROV2 system.")

- Strategy (S2, "Argue that risk posed by any remaining hazards is negligible") [Undeveloped]

- Strategy (S3, "Argue that no other risks have been identified for BlueROV2 system") [Undeveloped]

- Context (C1, "Definition of 'intolerable'")

- Goal (G3, "Risk from specified hazards has been reduced as low as reasonably practicable")

- Strategy (S4, "Apply ReSonAte to estimate level of risk from hazard conditions in BlueROV2.")

- Goal (G4, "Model of BlueROV2 system accurately describes possible propagation of specific hazards.")

- Goal (G6, "Possible hazard propagation paths correctly captured in BlueROV2 model") [Undeveloped]

- Goal (G7, "Barriers in the BlueROV2 model correctly describe their respective control action including any required system functions") [Undeveloped]

- Goal (G8, "All non-negligible threats have been identified in the BlueROV2 system") [Undeveloped]

- Goal (G5, "Quantitative risk estimates are accurate and below the acceptable threshold for BlueROV2 system.")

- Goal (G9, "State probability distribution used for risk estimation is an accurate representation of expected BlueROV2 system states") [Undeveloped]

- Goal (G10, "Estimated probability of catastrophic failure is below allowable threshold for severity class defined for BlueROV2.")

- Solution (Sn1, "Estimated risk level for BlueROV2 under defined operational conditions")

- Context (C2, "Assigned severity class based on identified hazards for BlueROV2") [Uninstantiated]

- Assumption (A1, "All functions required by BlueROV2 system are available and operational") [Uninstantiated]

```

\*\*Legend:\*\*

- [Undeveloped]: Marks goals or strategies that need further development.

- [Uninstantiated]: Indicates elements that still need information specific to the BlueROV2 system to be defined.

This tree represents an assurance case constructed from the generic pattern provided, tailored specifically for the BlueROV2 underwater remotely operated vehicle. Each goal, strategy, and context has been instantiated with specific system-related information. Moreover, the undeveloped parts of the assurance case should be developed as further information about the system is gathered or as detailed analyses are performed.