To create an assurance case for the BlueROV2 system using the provided assurance case pattern and display it in a hierarchical tree format using dashes (-), we need to instantiate the placeholders and relate the elements as per the hierarchy. Here is the assurance case tree for the BlueROV2 system:

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Goal (G1, Hazards for BlueROV2 system addressed in accordance with ALARP principle.)

- Strategy (S1, Argument by risk reduction/elimination of each hazard)

- Goal (G2, No intolerable risks present in the system)

- Context (C1, Definition of "intolerable")

- Strategy (S2, Argue that risk posed by any remaining hazards is negligible)

- Strategy (S3, Argue that no other risks have been identified)

- Goal (G3, Risk from any hazard has been reduced as low as reasonably practicable)

- Context (C2, Assigned severity class is BlueROV2.Hazard.Severity)

- Strategy (S4, Apply ReSonAte to estimate level of risk from hazard condition)

- Assumption (A1, Function BlueROV2 required by BlueROV2 BTD is available)

- Goal (G4, Model BlueROV2 BTD accurately describes possible propagation of hazard)

- Goal (G6, Possible hazard propagation paths correctly captured in BTD)

- Goal (G7, Barriers in the BTD correctly describe their respective control action including any required system functions)

- Goal (G8, All non-negligible threats have been identified)

- Goal (G5, Quantitative risk estimates are accurate and below acceptable threshold)

- Goal (G9, State probability distribution used for risk estimation is an accurate representation of expected system states)

- Goal (G10, Estimated probability of BlueROV2 Consequence is below allowable threshold for severity class)

- Solution (Sn1, Estimated risk level BlueROV2.RiskEst)

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The tree structure and relationships are depicted in the hierarchy using dashes, with nested levels indicating sub-goals, strategies, contexts, assumptions, and solutions as per the given predicates and rules. Note that most placeholders have been instantiated for relevancy to the BlueROV2 system, but some sub-goals remain undeveloped or uninstantiated as specified in the pattern.