

The reverse process of differentiation is known as **integration**.

To differentiate sums of terms of the form ax^n you multiply by the power then reduce the power by 1 to get nax^{n-1}

To **integrate** you do the exact opposite: you add 1 to the power then divide by the new power.

When you differentiate a constant, the result is zero. So when you perform an integration, you should add a constant, c , to allow for this. This is referred to as the **constant of integration**. The value of this constant can only be determined if further information is given.

Integrating x^n with respect to x is written as

$$\int x^n dx = \frac{x^{n+1}}{n+1} + c, n \neq -1$$

Key point

When you perform an integration you can check your result by differentiating it – you should get back to what you started with.

When a function is multiplied by a constant, the constant can be moved outside the integral.

$$\int af(x)dx = a \int f(x)dx \text{ where } a \text{ is a constant.}$$

Key point

When integrating the sum of two functions, each function can be integrated separately.

Given that displacement is a function of time $r(t)$, then velocity $v(t) = r'(t)$. Reversing this, we get

$$\int v(t)dt = r(t) + c$$

Key point

You may see this rule referred to as the *sum rule*.

$$\int (f(x) + g(x))dx = \int f(x)dx + \int g(x)dx$$

Given that velocity is a function of time $v(t)$, then acceleration $a(t) = v'(t)$. Reversing this we get

$$\int a(t)dt = v(t) + c$$

Key point

The Fundamental Theorem of Calculus shows how integrals and derivatives are linked to one another. The theorem states that, if $f(x)$ is a continuous function on the interval $a \leq x \leq b$, then

$$\int_a^b f(x)dx = F(b) - F(a) \text{ where } \frac{d}{dx}(F(x)) = f(x)$$

Key point