

This document describes how to use SPROM to generate the training samples. The platforms and configurations we used are Windows 7/8.1/10/11 and CUDA 9.0 respectively. The overall workflow is shown in Fig.1.



Fig. 1 SPROM workflow diagram

1. Open eeg64.exe and click the following buttons in sequence to start it.

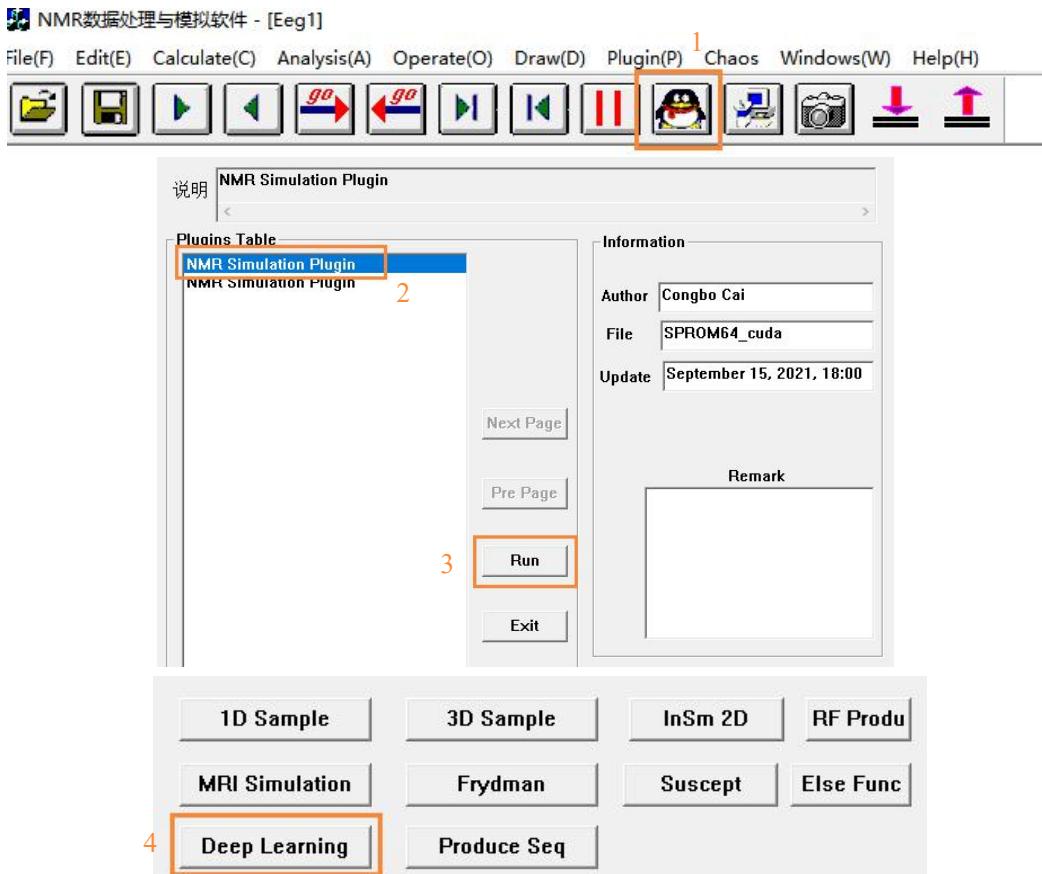


Fig. 2 The initial interface of eeg

2. Set the size of templates or load the parameters file ([./para/model.par3d](#)) directly.

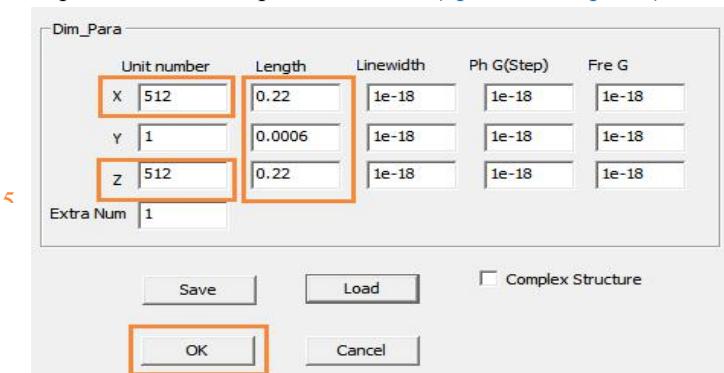


Fig. 3 The templates size setting interface

3. Set scan parameters or simply click “Load Param” button to load the parameter file ([./para/scanpar.sav](#)) directly.

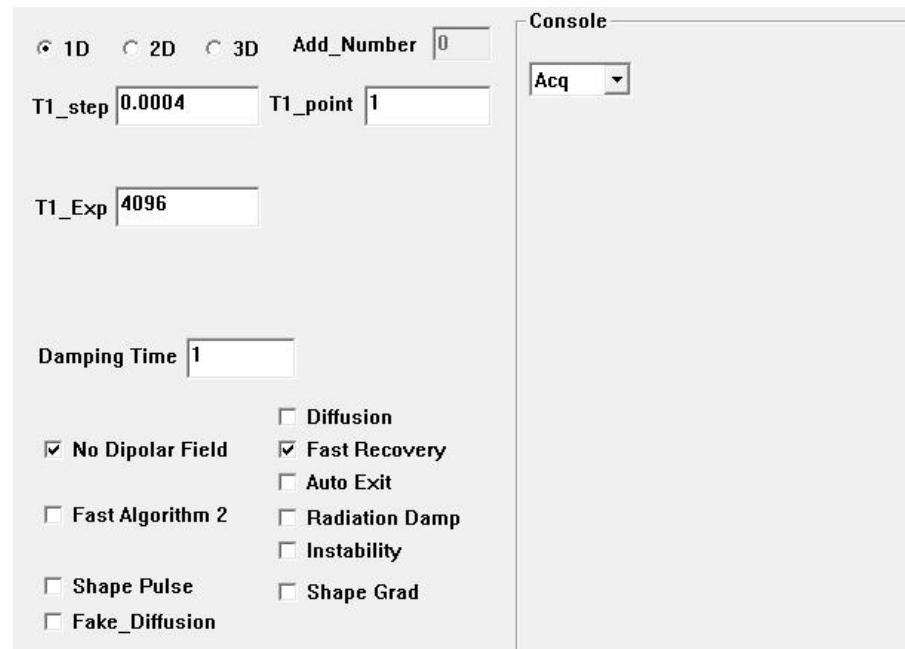


Fig. 4 The scan parameters setting interface

4. Sequence Loading.

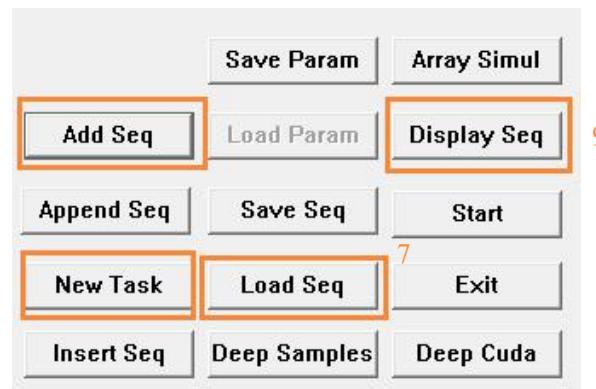


Fig. 5 The sequence loading interface

- 4.1 Click “Load Seq” button to load the sequence file ([SEMOLED_singe_train.seq](#)), and then click “Add Seq” button to accept this sequence loading.
- 4.2 Click “Display Seq” to show the sequence and check whether the sequence parameters are correct.

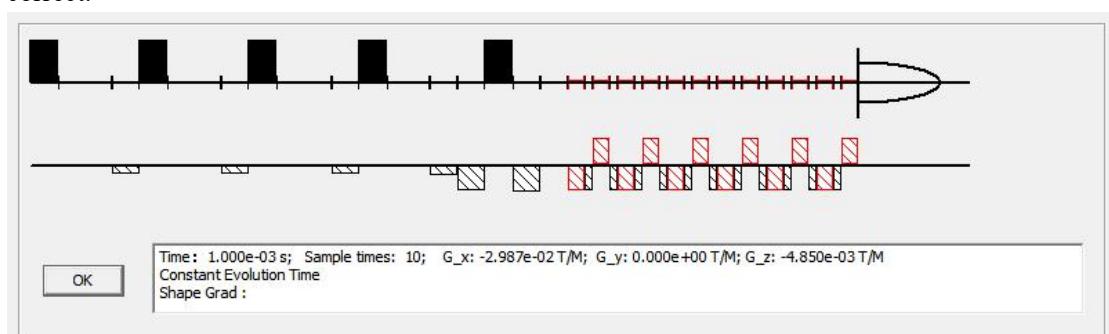


Fig. 6 A preview of MOLED sequence

4.3 Go to “New Task” to create a new task and repeat Step 4.1. Notice that select sequence files ([SEMOLED_single_train_shift_gradient.seq](#)) if gradient fluctuation for MOLED echo-shifting gradients is needed.

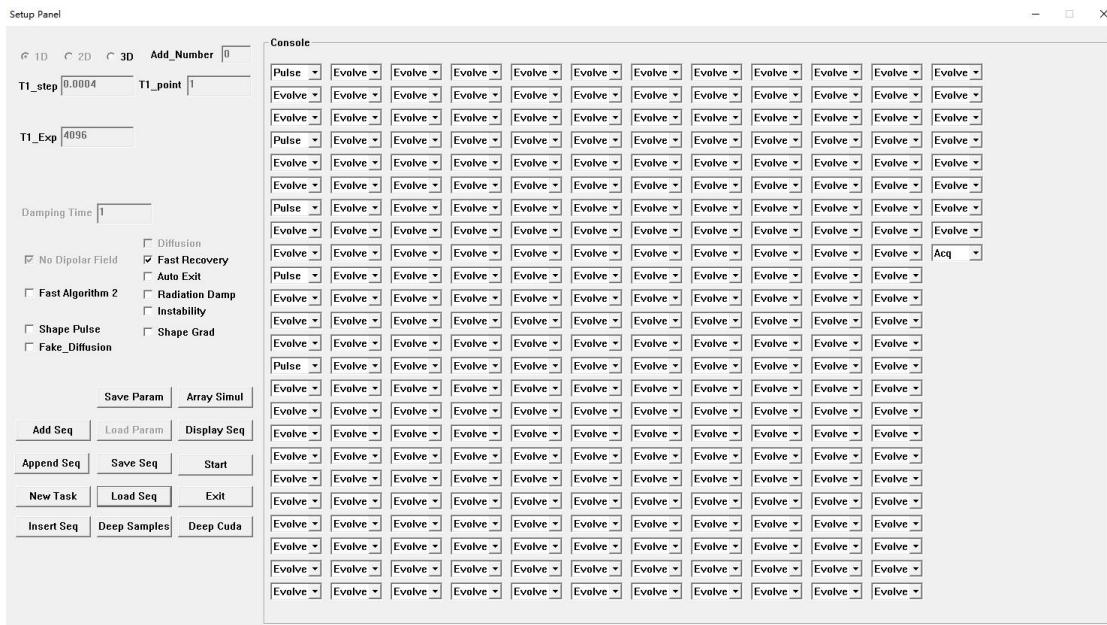


Fig. 7 The Main sequence design panel

5. Data generation

5.1 click “Deep Cuda”

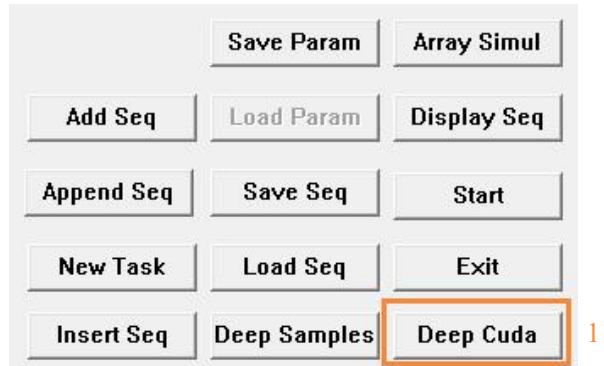


Fig. 8 The initial interface for generating data

5.2 Set the number of the generated samples (Here, the maximum value should not exceed 20000):



Fig. 9 The number setting interface

5.3 Enter the name of the storage path:

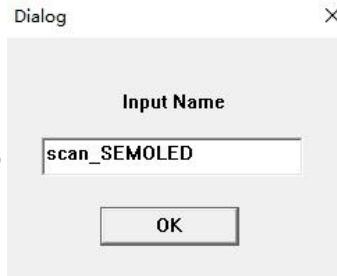


Fig. 10 The storage path setting interface

5.4 Set environment parameters:

- B1: inhomogeneous RF field
- Brain Pattern: select the human brain parametric templates
- Rand Pattern: parametric templates randomization
- Has Motion: subject movement
- Max_Vx(m/s): velocity of x direction
- Max_Vy(m/s): velocity of y direction
- Max_rot(rad/s): angular velocity.

Of course, you can simply import the parameters file ([./para/motion.dlp](#)) directly. Anyway, click the “OK” button at the end.

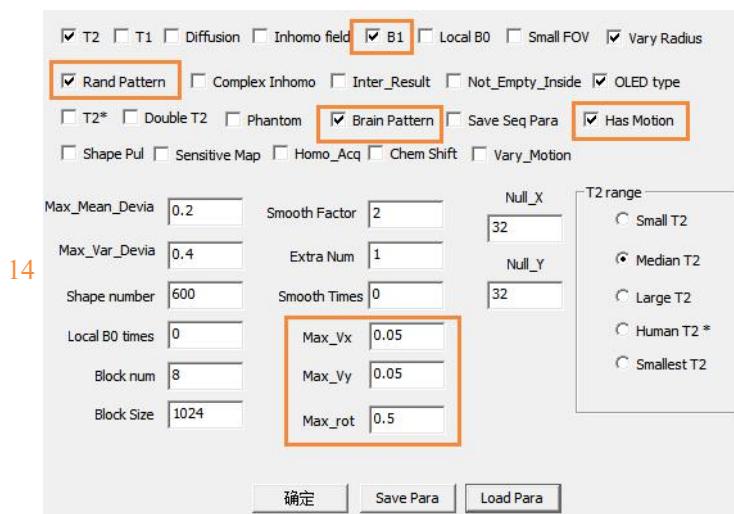


Fig. 11 The Simulation Settings Panel.

5.5 Enter the size of parameter templates, click “OK”, and then select M0 template ([.m0 file](#)) and T2 template ([.t2 file](#)) in sequence. After the selection, the simulation starts.

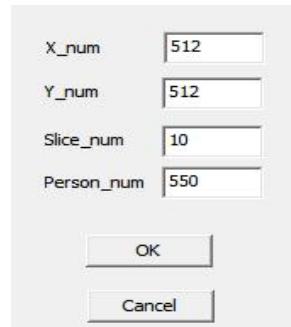


Fig. 12 The size of parameter templates setting interface

Output Files:

- | | |
|--|---|
| <ul style="list-style-type: none">❑ Team0.B1❑ Team0.m0❑ Team0.rot❑ Team0.T2❑ Team0.vx❑ Team0.vz❑ tempd_Team0.ccb | <ul style="list-style-type: none">• T2 templates: .T2 file• M0 templates: .M0 file• B1 field inhomogeneity templates: .B1file• Velocity of x direction: .vx file• Velocity of y direction: .vz file• Angular velocity: .rot file• Complex-value MRI signal: .ccb file |
|--|---|

Example code (MATLAB) for reading the outputs:

```
% .ccb file
fid_file = 'tempd_Team0.ccb';
origin_1D_data=load(fid_file, '-ascii');
origin_1D_complex=origin_1D_data(:,1)+1.0i*origin_1D_data(:,2);
origin_2D_complex=reshape(origin_1D_complex,[fre_num,phase_num]);
% parameters file
fid_file = 'Team0.T2';
fip_dif=fopen(fid_file,'rb');
[Array_2D_dif,num]=fread(fip_dif,inf,'double');
data_temp=Array_2D_dif(:,:,1);
data_temp=reshape(data_temp,model_num_x,model_num_y);
fclose(fip_dif);
```

Example code (MATLAB) for saving the parametric template:

```
T2=single(template_t2); % template_t2 is a 512*512*(slice*n) array
(fid,msg)=fopen('template.T2','wb');
fwrite(fid,T2,'float');
fclose(fid);
```

Reference:

- [1] C. B. Cai, M. J. Lin, Z. Chen, X. Chen, S. H. Cai, and J. H. Zhong, “SPROM - an efficient program for NMR/MRI simulations of inter- and intra-molecular multiple quantum coherences,” *C.R.Physique*, vol. 9, no.1, pp. 119-126, Jan. 2008.
- [2] C. B. Cai, C. Wang, Y. Q. Zeng *et al.*, “Single-shot T2 mapping using overlapping-echo detachment planar imaging and a deep convolutional neural network,” *Magn. Reson. Med.*, vol. 80, no. 5, pp. 2202-2214, Nov. 2018.
- [3] J. Zhang, J. Wu, S. J. Chen *et al.*, “Robust single-shot T2 mapping via multiple overlapping-echo acquisition and deep neural network,” *IEEE Trans. Med. Imag.*, vol. 38, no. 8, pp. 1801-1811, Aug. 2019.
- [4] Q. Q. Yang, J. C. Wang, J. F. Bao *et al.*, “Model-based synthetic data-driven learning (MOST-DL): Application in single-shot T2 mapping with severe head motion using overlapping-echo acquisition,” 2021. [Online]. Available: <https://arxiv.org/abs/2107.14521>.