

## **Additional materials for “Federica” hand project**

### **CAD files of the 3D printable components (.stl format)**

- **Hand palm**
  - o Hand\_palm.stl
- **Fingers**
  - o *Index finger folder*
    - IF\_distal\_phalanx.stl
    - IF\_middle\_phalanx.stl
    - IF\_proximal\_phalanx.stl
  - o *Middle finger folder*
    - MF\_distal\_phalanx.stl
    - MF\_middle\_phalanx.stl
    - MF\_proximal\_phalanx.stl
  - o *Ring finger folder*
    - RF\_distal\_phalanx.stl
    - RF\_middle\_phalanx.stl
    - RF\_proximal\_phalanx.stl
  - o *Pinky folder*
    - P\_distal\_phalanx.stl
    - P\_middle\_phalanx.stl
    - P\_proximal\_phalanx.stl
  - o *Thumb folder*
    - T\_distal\_phalanx.stl
    - T\_middle\_phalanx.stl
    - T\_proximal\_phalanx.stl
- **Pulleys**
  - o *Pulley A folder*
    - PA\_down.stl
    - PA\_up.stl
  - o *Pulley B folder*
    - PB\_down.stl
    - PB\_up.stl
  - o *Pulley C folder*
    - PC\_down.stl
    - PC\_up.stl
  - o Pulley\_D.stl
  - o *Pulley E folder*
    - PE\_down.stl
    - PE\_up.stl
  - o Pulley\_F.stl
  - o Pulley\_G.stl
  - o Servomotor\_pulley.stl
- **Levers**
  - o Lever\_A.stl
  - o Lever\_B.stl
  - o Lever\_C.stl
  - o Lever\_D.stl
  - o Lever\_joint.stl

### **Arduino code of the control system (.ino format)**

- control\_system\_code.ino